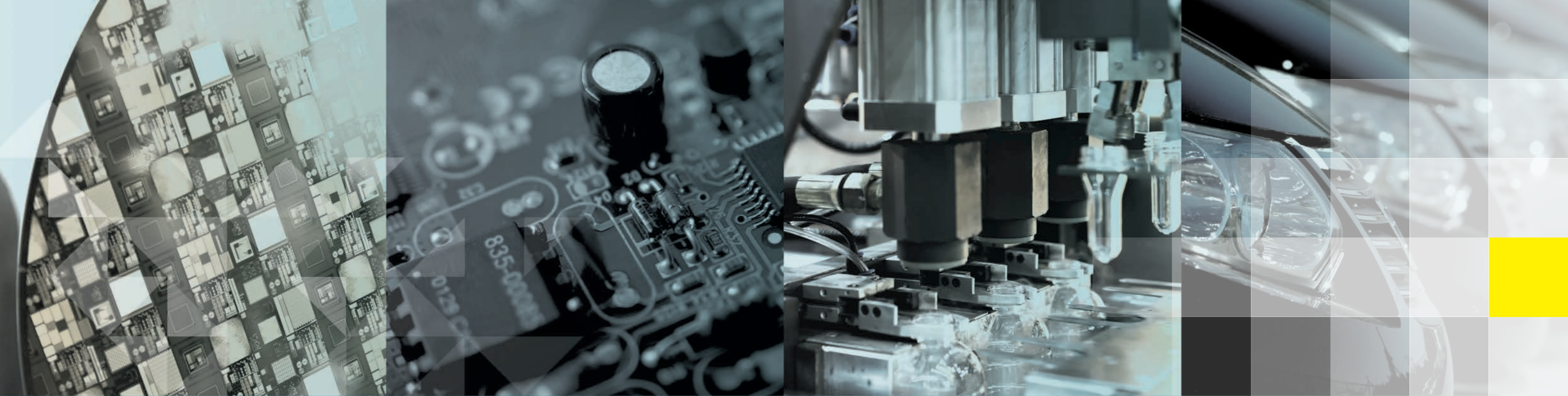




Leading Edge Controller

# FA-M3V

[www.yokogawa.com/itc](http://www.yokogawa.com/itc)



# FA-M3V

V I T E S S E <sup>TM</sup>

**Stress-free** solution from development through maintenance

## Speed

**Quadruple speed quest powered by two core technologies**

to deliver stable control at the highest speed

## Extensibility

**Extended functionality at high speed**

Network support, large volume data processing and easy data handling

## Reliability

**High reliability enables stable operation**

Hardware error check and correction (ECC) and single board design

## Fast

**Scanning 100K steps within 1ms**

The minimum scan time of 100µs is faster than microcomputer boards.

## Compact

**All-in-one CPU**

Ethernet, SD card and USB support are all condensed into a compact body.

## Smart

Range-free with max. **8,192 digital I/Os** and **856K device words**  
High performance and advanced functionality with high cost performance.

## Leading edge controllers

## The new FA-M3V series

**Created by stretching the High Speed IPRS design concept to new limits.**

The FA-M3 is designed and best known for its speed so it's only natural that the new series be named FA-M3V, where V stands for "Vitesse", which means speed in French.

From day one, FA-M3 has relentlessly pursued higher speeds as the most effective means to solving customer challenges.

Over time, this has evolved into the High Speed IPRS (Instruction, Processing, Response and Scan) design concept. Today, we have set a new record in this quadruple speed quest by creating the FA-M3V, which offers extensibility and reliability at incredible speed.

FA-M3V, the leading edge controller for customers who will settle for nothing less than the world's best.

\* The "V" in FA-M3V stands for "vitesse," which means speed in French

Leading Edge Controller





# Quadruple Speed Quest using Vitesse Engine & PIPS

## Delivering stable control at the highest speed

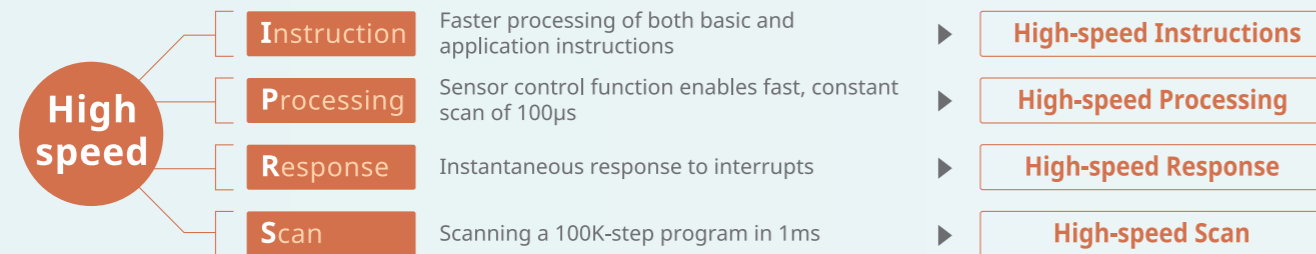
Featuring ultra high-speed, stable control, link functions and improved network performance, the FA-M3V controller is created by improving every aspect to deliver stable control at the highest speeds.



Sequence CPU module  
F3SP71-4S/F3SP76-7S

### Stretching the "High-speed IPRS" Design Concept

FA-M3V is the industry's fastest PLC in terms of CPU scanning speed. This incredible speed is made possible by stretching the High-speed IPRS (Instruction, Processing, Response and Scanning) design concept of the FA-M3 family of controllers and harnessing two Yokogawa core technologies, namely, the Vitesse engine and the parallel instruction processing system (PIPS).



### The FA-M3 Vitesse Engine

Supreme ladder processing capability

Fastest! **Scanning a 100K-step program in 1ms**

Basic instructions: **3.75ns min.** Application instructions: **7.5ns min.**

Floating-point Add instruction: **37.5ns** Minimum scan time: **100µs**

Resolution: **10µs** (when using the sensor control block)

Instruction Processing

Vitesse Engine  
for ladder processing

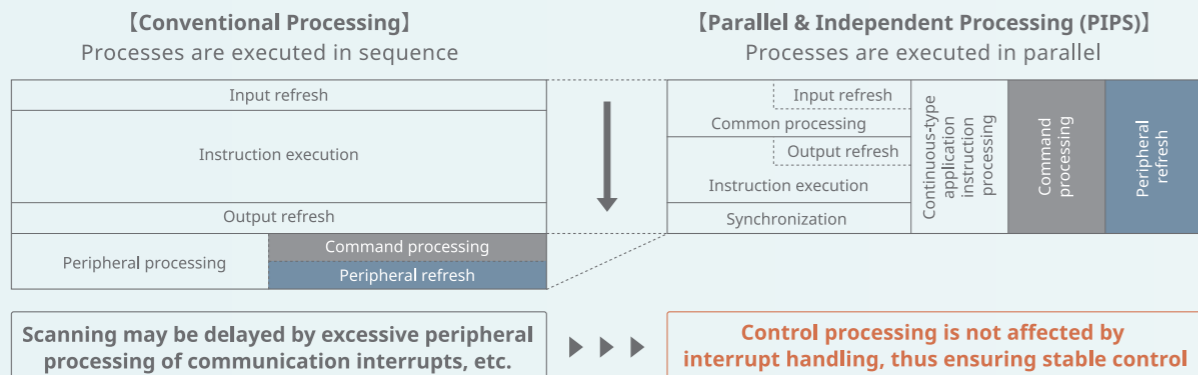


### Parallel & Independent Processing System (PIPS)

Fast, stable control for high quality production

Response Scan

With the Parallel & Independent Processing System (PIPS), ladder instruction processing and peripheral processing are carried out independently and in parallel. This ensures fast, stable control under all conditions for achieving high quality production.



### Enhanced High-speed IPRS (Instruction, Processing, Response and Scanning)

Quadruple speed quest based on the High-speed IPRS design concept

High-speed Instructions

#### Unrivalled High-speed Processing

3.75ns for basic instructions, 7.5ns for application instructions and 37.5ns for floating-point Add instruction

Faster processing of basic instructions enables reduced tact time using faster equipment, supports high-speed networking, enhances operability, as well as supports fault diagnosis and other advanced functions. In addition, faster application instructions widen utility to more applications. Floating-point addition instructions can also be speeded up to meet the requirements of high-precision applications.



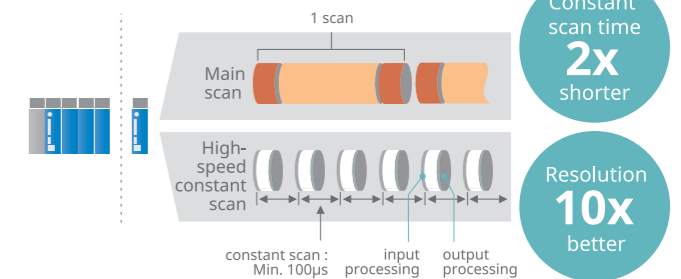
High-speed Processing

#### Max out Equipment Capability by Tuning

Sensor control function enables fast, constant scan from 100µs (10µs resolution when using SCB)

FA-M3V's sensor control function allows input, computation and output of one program block to be executed at constant intervals as short as 100µs, independently of the main scan, which may have a longer scan time due to advanced functionality of external devices.

The number of PLC units can be reduced since two ladder programs can be executed by one CPU module.

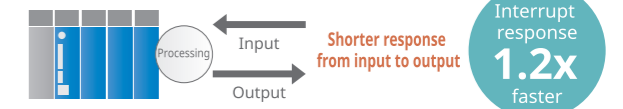


High-speed Response

#### Instantaneous Response to Interrupts

Interrupt response time of 85µs and digital filter from 0ms

With input response time of 85µs for interrupts from DC input modules, the FA-M3V can immediately respond to changes in inputs, enabling instantaneous high-speed control. Fast response (circuit delay 100µs min.) is achieved by focusing on total response time (input → program execution (processing) → output) and allowing variable time constants to be set to zero. Moreover, input response time of 10µs can be achieved with the use of a high-speed contact input module (F3XD16-3H).



High-speed Scan

#### Slashing Tact Time and Improving Quality

Scanning a 100K step ladder program in 1ms

The incredible speed of the FA-M3V of processing 100K ladder program steps within 1ms is achieved by analyzing its internal processes and striving for speed in every aspect. This translates into five times faster scanning for advanced device applications.



\* The quoted scan time is achievable under certain conditions. Actual scan time may vary with program processing and system configuration.

# Extended Functionality Coupled with Speed

## Network support, large volume data processing and easy data handling

Over and above fast, stable control, the FA-M3V delivers extended functionalities, including diverse network support, large file transfer and "PC-less" maintenance for improved productivity.

### Truly Range-free Controllers

The FA-M3 family of controllers is consolidated into two new CPU models of 60K-step and 260K-step program size so picking your ideal CPU is easy!

#### Sequence CPU Module(with network functions)

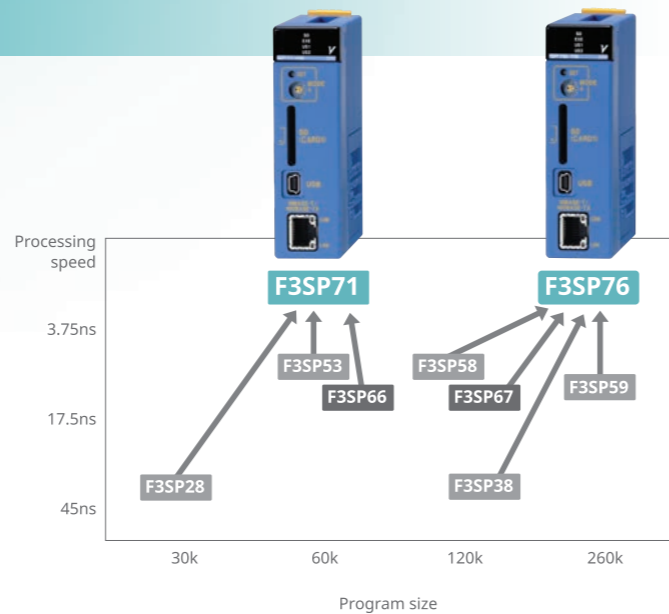
##### F3SP71

60K ladder steps, basic instruction 3.75ns min., built-in network functions

##### F3SP76

260K ladder steps, basic instruction 3.75ns min., built-in network functions

\* Use FA-M3 Programming Tool WideField3 (SF630-MCW) with these CPU modules.



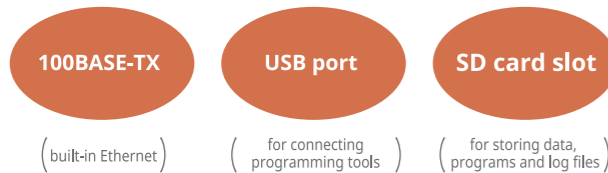
### Built-in Ethernet Network Support

Built-in Ethernet port for easy integration with manufacturing systems

#### Faster Ethernet Communication Processing

##### Built-in Ethernet Network Support

The built-in Ethernet port enables fast, stable communication. With a variety of functions condensed into an all-in-one CPU module, the FA-M3V offers cost advantages, a smaller footprint and networking that will not degrade control processing performance.

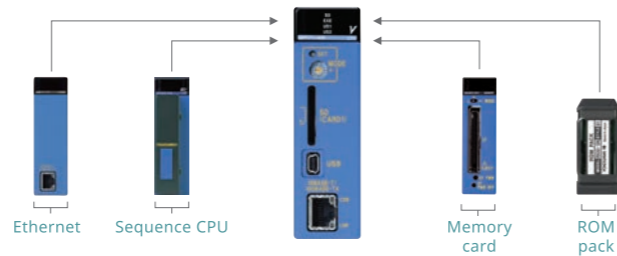


##### Enhanced Integration with Higher-level Systems

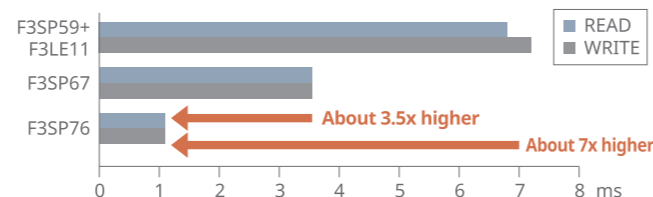
Fast communication response is achieved without compromising stable control. Scaling up to process large production data is simple.

- Much higher Ethernet throughput
- Large memory and SD memory card (SDHC compliant 32GB max.)
- Cache registers (1MB max.)
- Modbus/TCP Slave (server) function

##### All-in-one CPU module



##### Ethernet throughput comparison

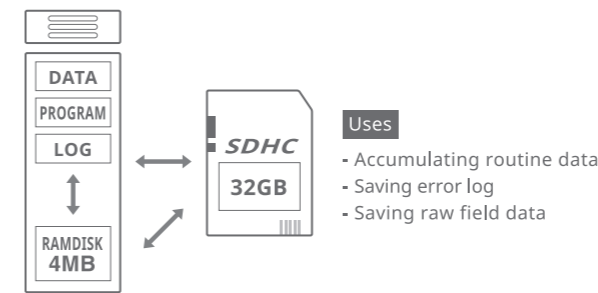


\* Comparison with older CPUs based on reading and writing 250 words of data

### Handling of Large Data

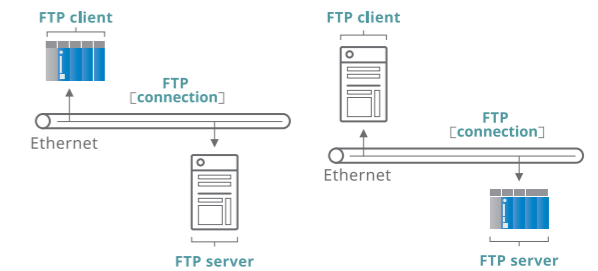
#### Built-in SD Memory Card Slot and RAMDISK

- Up to 32GB SDHC memory cards are supported for storing data, programs and log records as files.
- Redundancy of the file control area (FAT) reduces risk of file system damage due to power outage or card removal during writing.
- 4MB RAMDISK included for storing data and log records as files. (volatile memory)
- Off-the-shelf SD memory cards can be used.



#### FTP Client and Server Functions

- Data is transferred from CPU to host PC or server autonomously with no need for programming on the host PC or server. (client function)
- Data can be transferred from CPU to host PC by simply specifying parameters using a standard network protocol command interface. FTP server accesses and responses are logged for convenience of debugging and access management (server function).
- Batch file transfer replaces segmented data transmission.

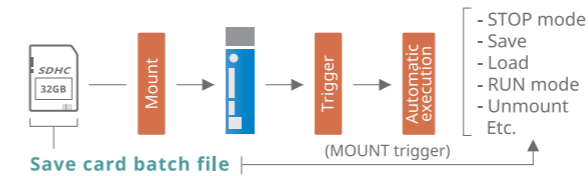


### "PC-less" Maintenance

#### Smart Access Function

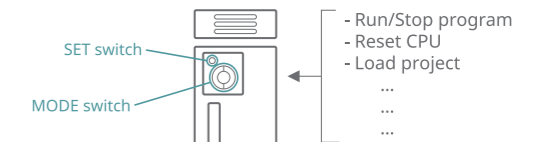
##### Card Batch File Function

Routine operations such as recipe loading or log acquisition for troubleshooting can be automatically executed simply by inserting an SD memory card. Batch commands coded in auto-execute files stored on a SD memory card can be automatically executed in response to various execution triggers (e.g. card insertion or error events, etc.)



##### Rotary Switch Function

Maintenance can be performed using the rotary switch and an SD memory card with no need for a PC, by simply turning a rotary switch (MODE switch) and pressing a push button (SET switch) on the front panel of the module.



### Easy Network and File Access

#### Network & File Processing Instructions

Handle large data easily by executing dedicated ladder instructions.

##### Instructions

- Socket (TCP/IP, UDP/IP) communications instructions
- FTP client instructions
- File operation instructions
- File access instructions
- Disk operation instructions

#### Virtual Directory Commands

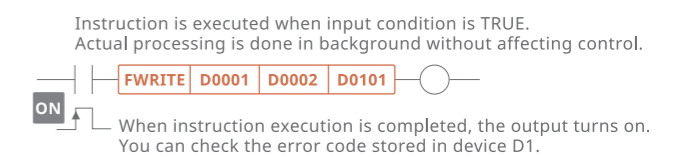
Get data, programs and log data as files from a host PC or server using FTP, without need for a ladder program.

Simply issue a command from a higher-level PC or server as shown below:

**Example** get %virtualYcmdYd2fcsv\_D101\_2\_128\_0\_6\_1\_0\_0\_4 data012.csv.  
(get 128 words of data starting from device D0101 as a data file in decimal representation and csv format)

#### Continuous-type Application Instructions

Time-consuming processing does not affect control processing.



#### Data Creation

Creation of transmission text and file data is made easy using the Constant Definition function (header file), which allows constant names to be defined with assigned numeric and string values separately from programs, and then coded in programs, and using the M3 Escape Sequence function, which allows binary representation codes to be included in character strings.



# High Reliability Enables Stable Operation

## Hardware ECC, single board design and enhanced security

High-precision calculation capability plus enhanced security with user management and operation log means even better reliability.

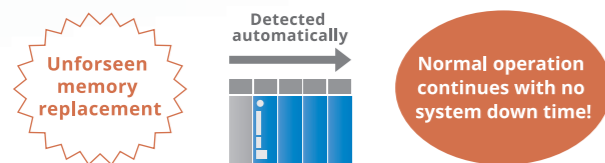
### High Precision, High Reliability Formidable computation power, user-friendly high-reliability design

Higher precision with more data digits, better reliability with built-in ECC

#### High-reliability Design for Reducing Failure Rate

##### SRAM Hardware Error Check and Correction (ECC)

- Hardware error check and correction (ECC) for the program execution area (within ASIC and external SRAM)
- ECC does not impair performance
- Improved reliability through patrol check\* (only for backup SRAM)



##### Use of Flash Memory

- Flash memory is used for storing programs. This minimizes the impact of memory data loss at power off.

##### Pursuit of Fundamental Reliability

###### Single board design

- Reducing the number of components fundamentally reduces the sources of failures.

#### High-precision Calculations

##### Operations preserving 32-bit significant digits

###### 64-bit integer arithmetic

- No need to convert all the way to floating point data for calculation

###### Double-precision floating point operations

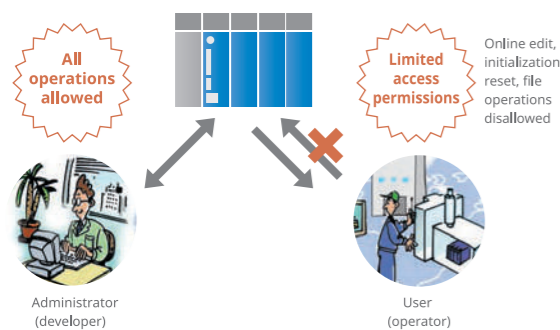
- Built-in floating-point unit (FPU) for floating-point operations
- No precision loss even if converted to floating-point data for calculations

### Security for protecting program assets and efficient fault analysis

Safeguards important customer assets by preventing unauthorized copying and keeping an operation log.

##### User management function

Appropriate access permissions can be defined for administrator, service and user personnel so that better security and work efficiency can be achieved concurrently.



##### Operation log function

The operation log function keeps a historical log of operations performed on the CPU module. With the user authentication function, the user name of the person performing an operation can also be recorded.

#### Operations performed on CPU can be checked using operation log.

| Operation log dialog |          |       |                 |             |           |
|----------------------|----------|-------|-----------------|-------------|-----------|
| Date                 | Time     | Route | Main Message    | Sub Message | User Name |
| 2010/06/11           | 08:53:22 | SWL_1 | Cpu Reset       |             | User      |
| 2010/06/11           | 10:02:14 | USB   | Download yjpt   | FTPPUT      | User      |
| 2010/06/12           | 11:06:20 | SIO   | Set a date-time |             | Service   |
| 2010/06/12           | 12:27:37 | ETH   | Switch Run mode | FTPPUT      | Service   |

When? Via? What? by whom?

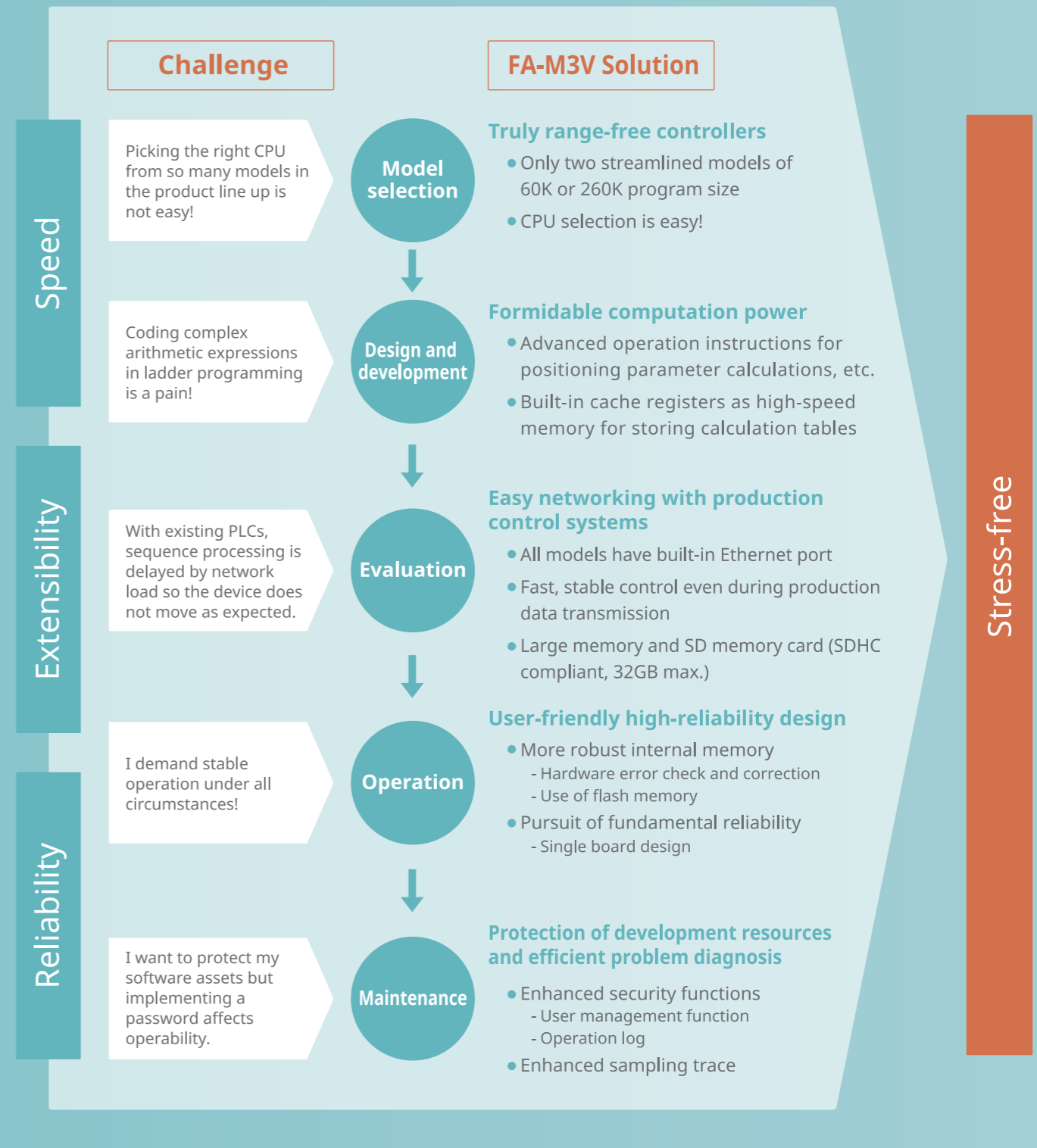
Existing network filter, CPU properties protection and function removal features are still available!

# FA-M3V Offers a Stress-free Solution

## for all process challenges from development through maintenance.

### Process Flow from Development through Maintenance

Starting right from CPU model selection all-the-way to maintenance after commissioning, the FA-M3V promises a stress-free experience by enabling development according to design and reducing development effort from ladder program design to engineering.

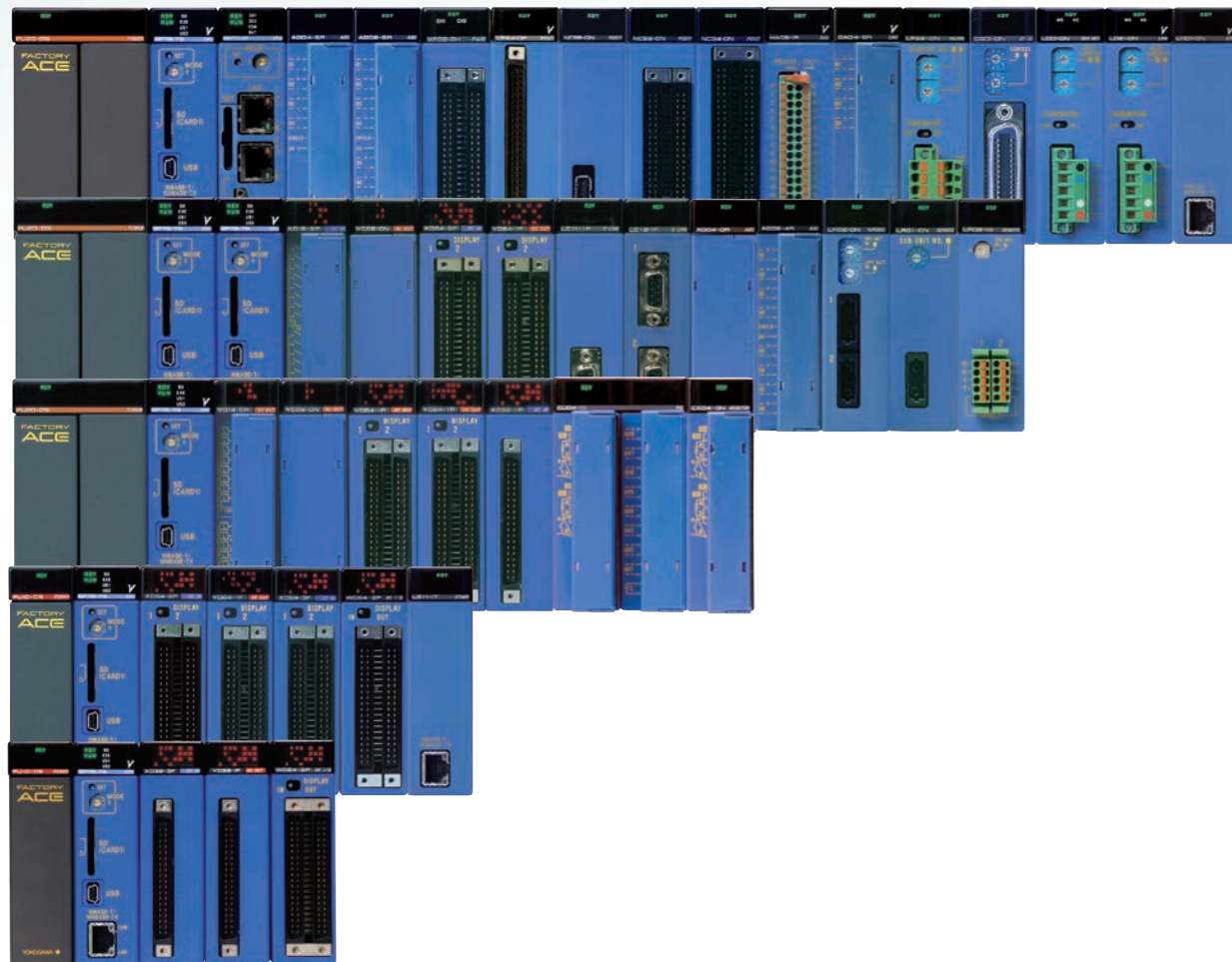


# Range Free

Simply combine modules to suit your applications!

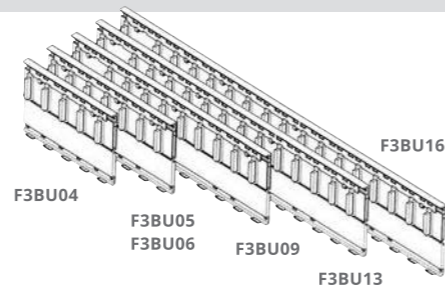
## Range-free controller covers versatile range of system in single model

The FA-M3 provides system expandability, unlimited by system size, and also allows the use of common spare parts. To expand the system, simply add desired modules, all of the same size. The installation leaves ample room within the control panel for standardization and efficiency improvement through panel design. With the FA-M3 PLC, a developer can give full rein to his creativity to build systems and realize control that fits his applications.



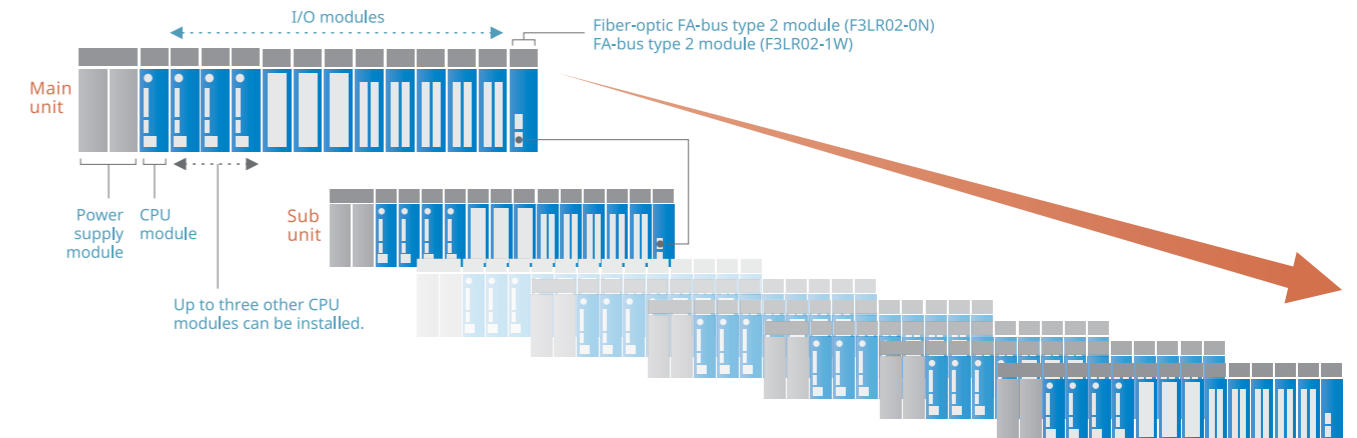
### Base Module F3BU04 / F3BU05 / F3BU06 / F3BU09 / F3BU13 / F3BU16

The FA-M3 offers six types of base modules, which allows flexible installation: 4-slot, 5-slot, 6-slot, 9-slot, 13-slot and 16-slot types.



## Main Unit and Sub-Unit

The main unit accommodates up to seven sub-units for installing additional I/O modules. This provides up to 8,192 range-free I/O points.



## Multi-CPU

Up to 4 CPU modules can be combined in a single unit

This capability to intermix different CPU module types in a single unit expands the existing PLC concept to offer greater versatility for system expansion. Up to four CPU can be accommodated. This feature is convenient when improving operating ratios of selected system components, integrating basic program data and other program data, dividing processing control, or selecting CPUs according to system scale or program size.

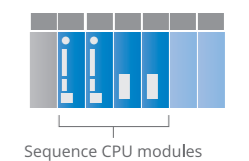


## Sequence CPU module



### F3SP71-4S / F3SP76-7S / F3SP22-0S

The FA-M3 accommodates up to four sequence CPU modules. This feature is convenient when improving operating ratios of selected system components, integrating basic program data and other program data, dividing processing control, or selecting CPUs according to system scale or program size. What's more, you can freely intermix sequence CPU modules with other types of CPU modules.





# Advanced Programming Support

## Efficient program design from development to maintenance

FA-M3 Programming Tool WideField3 SF630-MCW

New, useful functional enhancements based on user requirements

Improving program development efficiency is a common concern of all PLCs. The latest FA-M3 Programming Tool WideField3 is designed to harness the incredible power and speed of the FA-M3V. Its new features include balloon comment and monitor for more convenient programming, as well as the cross reference and script functions for more efficient programming. Besides engineering support function is added for efficient debugging.

\* Ladder program created with WideField and WideField2, as well as sequence CPU modules running these programs can be used as-is with WideField3  
 \* Windows10 (x86/x64) is supported from WideField3 R4.01 or later

### Various functions are provided to facilitate easier program reuse, debugging and maintenance

Execute often used commands directly from the Find/Comparison toolbar

Intuitive operation using visual icons

Efficient development with multi-window support

Refer to file/data structure during operation

Allows constant monitoring of CPU status.

Switches view between offline and online modes

### Script Coding and Monitoring

#### Complex calculation processing made easy!

Computations and text manipulations can be programmed using script code, which is converted automatically into ladder code before execution. Moreover, used devices can be monitored within script code for efficient debugging, and mnemonics can be entered in script code for even more powerful programming!

#### Script monitoring simplifies online debugging

Used devices can be monitored along with script code.

#### Efficient programming using script instructions and functions!

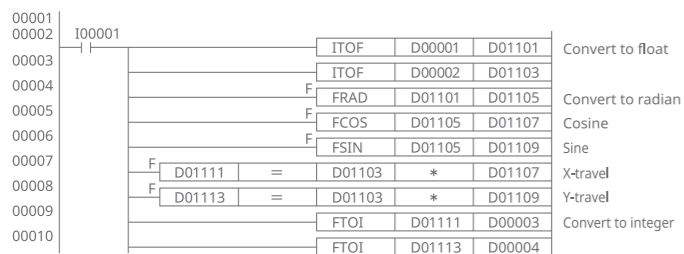
| Operators and reserved words | Script functions  |
|------------------------------|---|
| Arithmetic +, -, *, /, MOD   | Basic Rising bit  |
| Comparison </>, >=, <=, <>   | Calculation Trigonometric, logical, exponential functions, etc. |
| Logical NOT, AND, OR, XOR    | Data processing Rotate, move, convert, byte operations, etc.    |
| String &, ==, <>             | String manipulation Search, insert, replace, concatenate, etc.  |

**Inline mnemonic**

B : Bit, S: character string  
 W : word, L: long word, D: double long word  
 F : single-precision floating point, E: double-precision floating point

#### Coding of complex computations and data processing made easy!

[To calculate the X-travel and Y-travel from travel distance and angle]



[To calculate the X-travel and Y-travel from travel distance and angle]

```
// To calculate the X-travel and Y-travel from travel distance and angle //
W.D00003 = W.(COS(RAD(F.D00001)) * F.D00002)
W.D00004 = W.(SIN(RAD(F.D00001)) * F.D00002)
```

Scripting improves programming efficiency and program readability!

### Balloon Comment and Device Monitoring

#### Place balloon comments and monitors anywhere like post-it notes

Operation history, handover memos, etc. can be written as comments and placed on circuits freely like post-it notes in any specified font, color and size, even transparently so that underlying circuits are visible. Devices can even be specified within comments to allow device monitoring anywhere!

A device within a balloon comment can be monitored anywhere.

Comments can be displayed anywhere, in any font, even transparently.

### Cross Reference

#### Cut debug man-hours! Prevent regressive programming

The cross reference function enables real-time display of devices used in a program. Moreover, by simplifying the search for used devices, it saves time and prevents missed-out amendments during programming and program modification.

#### Cross reference search object

Address, tag name, constant definition, structure name (including structure member names), block/macro name and label

Jump to corresponding circuit with one click!

Search and list all places where a device is used

### File Comparison

#### Better use of design assets

The file comparison function enables offline comparison of data between two projects. It is useful for reuse management and revision control by comparing against past design assets, as well as for maintenance by comparing against field programs. Program comparison results are displayed on ladder diagrams with circuit lines containing differences highlighted for easy identification.

Comparison can be made for Lines containing differences are highlighted all data between two projects. in ladder diagrams for easy identification.

Ladder programs can be edited and re-compared for easy synchronization with past assets.

Matching lines are displayed side-by-side for easy comparison.

### Other convenient functions

#### Circuit comment-out

Selected instructions or circuits can be short-circuited or disabled temporarily.

Activated instruction Inactivated instruction

Disabled instruction

Disabled circuit

#### Operation protection, operation log

Operation protection function enables to set CPU operation available user and to store operation log.

Operation protection configuration

Operation log viewing

# Realistic Debugging Environment

## Dynamic and flexible simulation

FA-M3 Simulation Software Virtual-M3 SF681-MDW

Great performance for debugging and troubleshooting

The Virtual-M3 is a simulation software which runs ladder sequences on a PC and debugs programs without any real machine. The I/O module simulation function, link function with HMI, step operation function, and link function with Live Logic Analyzer drastically reduce the debugging time.

\* This supports WideField3 R4.01 or later.



### Realistic Debugging Environment Supporting Simulated External Devices

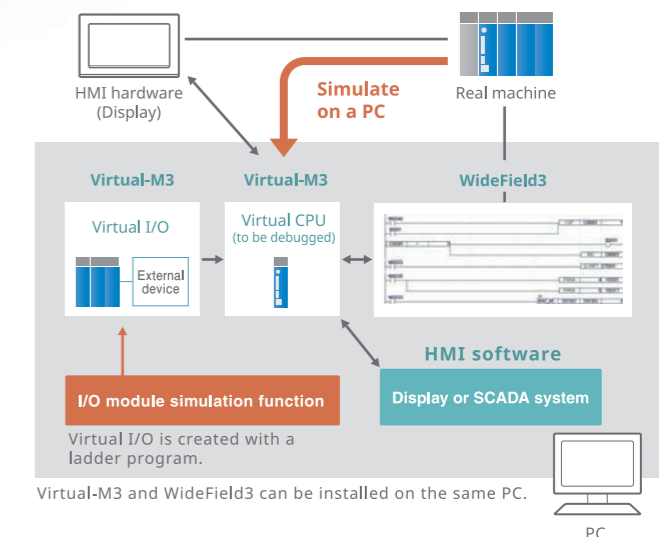
#### I/O module simulation function

- Two Virtual-M3 windows are opened. One works as a virtual CPU to be debugged and the other works as a virtual I/O that simulates I/O modules and external devices. The virtual CPU can be debugged while the virtual I/O is running.
- The simulation is not only for a CPU module but also for I/O (virtual I/O), and therefore can result in a more realistic debugging environment.
- Programs for the virtual I/O module can be created by the WideField3.
- The I/O module simulation function can work with (manually) simulated input.

#### Connection with HMI

- The higher-level link function can be used to connect with an HMI (display) or a SCADA system.
- The program of HMI (display) and SCADA system can be debugged with Virtual-M3.
- The Virtual-M3 can connect to HMI software through a routing connection inside PC and HMI hardware through a LAN port on the PC.

#### Debugging environment



Virtual-M3 and WideField3 can be installed on the same PC.

### Flexible Debug Operation and High-speed Performance

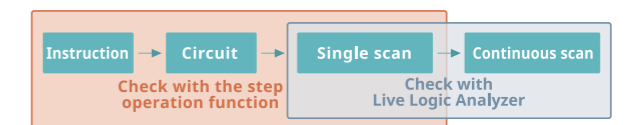
#### Step operation functions

- Check the program performance per instruction, circuit, and scan.
- The high performance step operation can respond to continuous operations without delay.
- The concentrated point can be debugged repeatedly.
- The [Restore to Previous State] action can undo up to 128 steps or the previous status of the execution during the debugging. And it allows users to skip some steps and restart from the preferred position.
- The data can be changed during the step operation and it enables the check of the performance under various conditions.

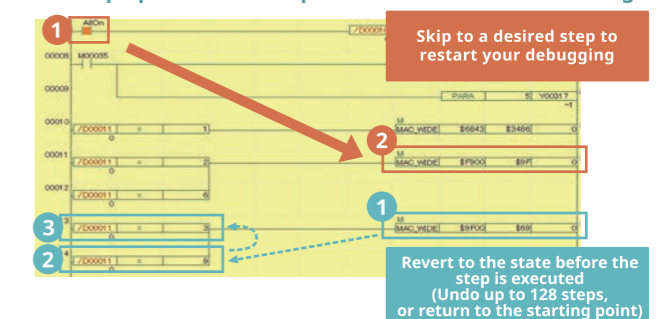
#### Connection with Live Logic Analyzer

- Live Logic Analyzer in WideField3 can be used for simulation.
- The signal behavior of one scan or a number of continue scans can be checked by the waves in LLA.
- The change within one scan can be checked by waves using the combination of step execution.

#### Check by each instruction, circuit, and scan



#### The step operation can repeat a desired section to debug



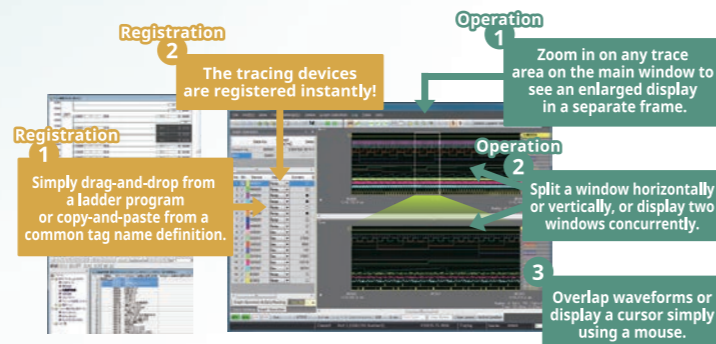
### Live Logic Analyzer function

\* for WideField3 R3.01 or later  
\* for F3SP71-4S/F3SP76-7S only (R4.01 or later)

#### User-friendly engineering feature to leapfrog your debugging

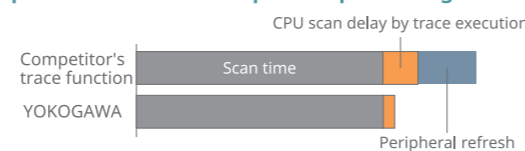
The live logic analyzer stores the status and contents of devices designated for sampling in the trace buffer memory, as the sampling trace tool does, and immediately displays the trace results. Trace results can be displayed in scan chart format while ladder program running high speed application concurrently.

#### Easy registration, configuration and operation

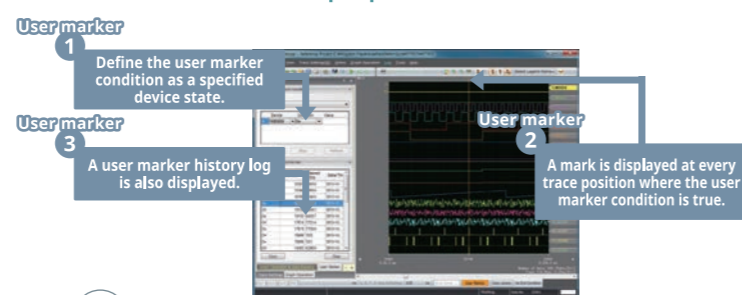


(More!) Trace results can be saved as a screen image or in CSV format.

#### No impact on CPU scan with parallel processing



#### User marker enables pin-point search of massive trace data



(More!) You can instantly jump to and center the display on any user marker or any user-defined cursor

#### Upgraded trace function by high-speed communication

- Up to 96 data points (64 relays and 32 registers) can be traced concurrently.
- Large sampling capacity up to 1M samples per channel
- Even advanced-function I/O devices can be traced.
- Once started, trace result can be displayed anytime, allowing concurrent program debugging even during tracing.

#### Traces equal to actual production performance

- Minimized trace execution impact on the CPU scan.
- The trace runs with minimal impact on the CPU scan and thus reflects actual production performance.
- USB and Ethernet peripheral processing run in parallel independently without affecting the CPU scan.

#### High degree of usability by powerful HMI

- Easy registration, configuration and operation.
- User marker enables pin-point search of massive trace data.
- Zoom in on any trace area on the main window, split a window horizontally or vertically.

### Sampling Trace

#### Advanced analysis environment with oscilloscope-like view

The sampling trace function collects the device data of the sequence CPU module and the advanced I/O module, and displays all collected data at a time after the completion of the data collection, and confirms the change of the device data. It is effective for a data trace with fixed starting timing, and for a trace that has to wait the expected phenomenon for a long time.

#### Comparison of Trace Functions

| Function                              | Live Logic Analyzer   | Sampling Trace   |
|---------------------------------------|---|--|
| CPU connection I/F                    | Ethernet/USB  | Ethernet/USB/FL-net  |
| Toolless trace                        | N/A   | Card batch/virtual directory   |
| Sampling method                       | Scan/periodic/TRC instruction                                 | Scan/periodic/TRC instruction  |
| Save destination of trace results     | CPU module: N/A<br>WideField3: Dedicated file format/CSV file | CPU module: CPU memory/SD card<br>WideField3: Dedicated file format/CSV file |
| Trace start condition setting         | None  | Available  |
| Trace end condition setting           | Can be enabled or disabled (Disabled by default)              | Can be enabled or disabled (Enabled by default)                              |
| Number of devices to be traced        | Relay: 64 points<br>Register: 32 points                       | Relay: 64 points<br>Register: 128 points                                     |
| Data display timing                   | During a trace  | After a trace is completed   |
| Data display method                   | Dynamic chart   | Static chart   |
| Data display format                   | Bit/decimal/hexadecimal/float/double precision float          | Bit/decimal/hexadecimal  |
| Zoom in                               | Available   | Available  |
| Trace start by configuration settings | N/A   | Available  |

\* It is not possible to perform both sampling trace and live logic analyzer simultaneously on a CPU.



# Open Network

## Compliant with a diverse range of open networks

### Information Network

#### Ethernet Interface Module

F3LE01-1T / F3LE11-1T / F3LE12-1T



#### Automatic response to request Emails (F3LE11-1T)

With the Ethernet interface module, remote maintenance and engineering (OME) is only an Email away. When equipment failure occurs, an Email is automatically transmitted to the user. From a host computer, the user sends request Emails to read or write various statuses, read user logs and system logs, or uses the trace function to obtain up-to-date information on the system status. This significantly shortens the time required to resolve field problems. By using this module with FA-M3 Programming Tool WideField3 and other software, building an OME environment becomes a simple task. This module not only supports 10Mbps communications, but also high speed communications at 100Mbps, compliant to the 100BASE-TX standard.

| Item                  | Specifications            |   |                             |
|-----------------------|---------------------------|---|-----------------------------|
|                       | F3LE01-1T                 | F3LE11-1T   | F3LE12-1T                   |
| Protocol              | TCP/IP, UDP/IP, ICMP, ARP | TCP/IP, UDP/IP, ICMP, ARP, SMTP/POP3, HTTP1.0                             | TCP/IP, UDP/IP, ICMP, ARP   |
| Access control method | CSMA/CD                   |   |                             |
| Transmission rate     | 10Mbps                    | 100Mbps, 10Mbps   |                             |
| Transmission mode     | Baseband                  |   |                             |
| Max. segment length   | 100m*                     |   |                             |
| Functions             | Event transmission        | Email response, automatic transmission of alarm emails, password function | Messaging (UDP/IP) function |

\* The length between the HUB and the module

#### Easy Remote Equipment Maintenance by Emails Ethernet-based Remote OME

The remote OME (Remote Operation, Maintenance & Engineering) function utilizes communications via the Ethernet, the de-facto standard for open networks, to deliver a wealth of solutions. Information such as images and audio can be captured and transmitted to allow efficient verification of the system status. This relieves developers of headaches such as excessive man-hours required for minor problems, frequent system support trips and delayed system failure information.

\* Remote OME (Remote Operation, Maintenance & Engineering) refers to a mechanism that enables remote maintenance of equipment at distant sites. It is a concept proposed by Yokogawa and is a registered trademark of Yokogawa Electric Corporation.

#### NX Interface Module

F3NX01-2N



#### Support for Autonomous Distribution Protocol

The NX Interface Module enables connection to a NeXUS Autonomous Distribution\*1 system. By supporting the Autonomous Distribution Protocol, it enables information interchange between FA-M3 systems and connections to PC, FA computers and other external devices that support the Autonomous Distribution protocol.

\*1: "Autonomous Distribution" is a registered trademark of Hitachi Ltd.

| Item                   | Specifications    |
|------------------------|-------------------|
| Protocol               | UDP/IP, ICMP, ARP |
| Access control method  | CSMA/CD           |
| Transmission rate      | 100Mbps, 10Mbps   |
| Transmission method    | Baseband          |
| Maximum segment length | 100m *2           |

\*2: Maximum distance between the module and a hub.

### Control Network

#### EtherNet/IP Interface Module

F3LN01-0N



#### Global Industrial Ethernet

This interface module conforms to "EtherNet/IP" (Ethernet Industrial Protocol) which is an open standard of industrial Ethernet promoting by ODVA (ODVA, Inc)

It is part of the IEC61158 international standard and approved as SEMI standard E54.13.

Highly-extensible system configuration allows devices ranging from simple sensors and actuators to complex information systems to be connected in a multi-vendor environment. Multiple EtherNet/IP modules can be mounted on one system to separate control and information networks, or implement network redundancy.



| Item                          | Specifications               |
|-------------------------------|------------------------------|
| Protocol                      | CIP Protocol                 |
| Physical Layer                | 100BASE-TX, 10BASE-T         |
| Transmission speed            | 100Mbps, 10Mbps              |
| Maximum segment length        | 100m*                        |
| No. of sessions / connections | 128                          |
| Functions                     | EtherNet/IP scanner, adapter |

\* Maximum distance between the module and a hub.

#### FL-net Interface Module

F3LX02-2N



#### Build a multi-vendor system with ease

The FL-net interface module is compliant with FL-net (OPCN2) version 2.00, an open FA network standard defined by Japan Electrical Manufacturers' Association (JEMA). It allows a user to easily build a multi-vendor system, and communicate using cyclic transmission and/or message transmission.

Moreover, by connecting a PC running the WideField3 software, a user can perform maintenance and debugging by using WideField3 functions to monitor ladder programs, read/write devices, read log files and trace program execution.

| Item                     | Specifications                                 |
|--------------------------|--|
| Protocol                 | UDP/IP FA link, ICMP, ARP                      |
| Access control method    | IEEE802.3 (CSMA/CD) compliant                  |
| Transmission rate/medium | 100Mbps, 10Mbps/IEEE 802.3 compliant           |
| No. of nodes             | 254 max.                                       |
| Transmission method      | Base band                                      |
| Cyclic transmission      | 512 words for area 1<br>8,192 words for area 2 |
| Messaging                | 1,024 bytes max.                               |

### Device Network

#### DeviceNet Interface Module

F3LD01-0N



#### Improve productivity using multi-vendor network

This interface module conforms to "DeviceNet", which is a global standard of open field networks promoting the spread of ODVA (ODVA, Inc).

It is also adopted by SEMI (Semiconductor Equipment and Materials Institute) as the standardized sensor bus. The module transfers ON/OFF data, analog data, tens of bytes of data or setup/maintenance information, and allows connection of up to 63 compatible devices of worldwide manufacturers with a maximum transfer rate of 500kbps and a maximum transmission distance of 500 meters (at 125kbps). It supports a wide range of applications with flexibility and brings dramatic improvements in productivity and maintainability.

| Item                  | Specifications  |
|-----------------------|---|
| Interface             | DeviceNet compliant   |
| Transmission rate     | 125/250/500kbps (selectable by switch)  |
| Transmission medium   | 5-wire cable<br>(2 for signals, 1 for SHIELD and 2 for power)   |
| Transmission distance | Maximum cable length for main line: 500m<br>(Transmission rate: 125kbps when using only thick cables) |
| Connection method     | Multi-drop, T-junction  |
| No. of nodes          | 64 (including master)   |

#### CAN 2.0B Interface Module

F3LD21-0N



#### Support for CAN2.0B protocol

This module is an interface module for connecting to CAN\* (Controller Area Network).

CAN is the communication standard designed for noise resistance and used for data communication between interconnected devices. It was developed as a means of communication between in-vehicle devices, but now it is recognized for its reliability, sophisticated fault detection function, etc., and is drawing attention in a wide range of fields.

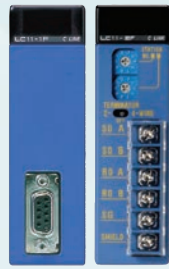
\* CAN was proposed by Bosch of Germany and later standardized as ISO 11898 and ISO 11511 by the International Organization for Standardization (ISO).

| Item                     | Specifications   |
|--------------------------|--|
| Interface                | CAN2.0B format   |
| Support frame            | Only data-frame supported  |
| No. of channels          | 1 channel  |
| Transmission speed       | 125k/250k/500k/1Mbps   |
| Transmission media       | 5 dedicated lines<br>(2signal, 1shield, 2 power lines)   |
| Connection configuration | Multidrop or T-Branch system   |
| Functions                | Automatic periodic transmission<br>Manual transmissions<br>Automatic reception data storage                            |
| No. of available IDs     | For automatic periodic transmissions: 15 IDs max.<br>For manual transmissions: No limit<br>For reception: 320 IDs max. |

## Serial Communications

### Personal Computer Link Module

F3LC11-1F / F3LC12-1F / F3LC11-2F



#### Ideal for connecting to PCs or displays

This communications module implements PC link functions to a display or host computer, such as a personal computer via an RS-232-C or RS-422-A/485 interface. It allows reading from and writing to all FA-M3 devices, even when no ladder program is executing. You may also read various program-related information and error logs. With the F3LC11-2F, up to 32 FA-M3 units may be connected to host computer.

| Item                  | Specifications  |                  |                                     |
|-----------------------|---|------------------|-------------------------------------|
|                       | F3LC11-1F   | F3LC12-1F        | F3LC11-2F                           |
| Interface             | EIA RS-232-C compliant  |                  | EIA RS-422-A / EIA RS-485 compliant |
| Transmission mode     | Half-duplex   |                  | Half-duplex, 4-wire/2-wire          |
| Transmission distance | Total distance: 15m   |                  | Total distance: 1,200m              |
| Transmission rate     | 300 / 600 / 1,200 / 2,400 / 4,800 / 9,600 / 14,400 / 19,200 / 28,800 / 38,400 / 57.6k / 76.8k / 115.2kbps |                  |                                     |
| No. of units          | —   |                  | 32 max.                             |
| No. of ports          | 1 (non-isolated)  | 2 (non-isolated) | 1 (isolated)                        |

\* Usable with YHLS cable(KM80/KM81)

### Modbus Interface Module

F3LC31-2F



#### Support for Modbus protocol

This module is an interface module for Modbus\* RTU/Modbus ASCII communication. This module has the master functions of Modbus communication and enables to communicate with various slave devices in the market. It also supports slave functions that realize to communicate with other brand's master devices.

\* "MODBUS" is a registered trademark of Schneider Automation Inc.

| Item                   | Specifications  |
|------------------------|---|
| Interface              | EIA RS-422-A / EIA RS-485 standards.                                |
| Transmission mode      | Half-duplex, 4- or 2-wire system                                    |
| Transmission speed     | 300/600/1200/2400/4800/9600/14400/19200/28800/38400/57.6k/115.2kbps |
| Transmission media     | Shielded twisted-pair cable (AWG20-16)                              |
| Transmission distance  | 1200m Max.  |
| No. of ports           | 1 (isolated)  |
| Communication protocol | Modbus RTU/Modbus ASCII   |

### Ladder Communications Module

F3RZ81-0F / F3RZ82-0F / F3RZ91-0F



#### High-speed serial communications up to 115.2kbps

This module enables control of remote devices by ladder programs of a sequence CPU module using RS-232-C, RS-422-A or RS-485 communications. The F3RZ81-0F/F3RZ82-0F module uses a D-sub 9-pin connector and allows transmission up to 15m, while the F3RZ91-0F module uses a terminal block and allows transmission up to 1,200m.

| Item                    | Specifications  |                  |   |
|-------------------------|---|------------------|---|
|                         | F3RZ81-0F   | F3RZ82-0F        | F3RZ91-0F   |
| Interface               | EIA RS-232-C compliant  |                  | EIA RS-422-A / EIA RS-485 compliant                   |
| Connection              | Point-to-point  |                  | Point-to-point (also supports multi-point connection) |
| Transmission mode       | Full/half duplex  |                  | Full/half duplex, 4-wire/2-wire                       |
| Synchronization mode    | Start-stop synchronization  |                  |   |
| Communications protocol | None  |                  |   |
| Transmission rate       | 300 / 600 / 1,200 / 2,400 / 4,800 / 9,600 / 14,400 / 19,200 / 28,800 / 38,400 / 57.6k / 76.8k / 115.2kbps |                  |   |
| Transmission distance   | 15m max.  |                  | 1,200m max  |
| No. of ports            | 1 (non-isolated)  | 2 (non-isolated) | 1 (isolated)  |

\* Usable with YHLS cable(KM80/KM81)

### GP-IB Communications Module

F3GB01-0N



#### Ideal for automation of inspection system

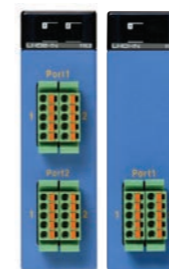
- Performs both measurement and control within a compact body.
- Delivers a high-speed inspection system.
- Enables simple, high-speed communications with GP-IB devices.
- Enables communications with GP-IB devices using only ladder sequences.

| Item                  | Specifications                         |                               |
|-----------------------|--|-------------------------------|
| Interface             | ANSI/IEEE Standard 488                 |                               |
| Transmission mode     | 8-bit parallel, half-duplex            |                               |
| Connection type       | Star, multidrop                        |                               |
| No. of devices        | 15 Max.                                |                               |
| Handshaking system    | 3-wire handshaking                     |                               |
| Transmission distance | Total cable length                     | 20m max.                      |
|                       | Between devices                        | 4m max.                       |
|                       | Total distance by devices              | 2m max. (x number of devices) |
| Interface             | 24-pin receptacle connector (IEEE-488) |                               |
| Setting               | Device address                         | 0 to 30                       |
|                       | Delimiter code                         | CR+LF, CR, EOI or Others      |
|                       | Controller                             | Yes or No                     |

## High-speed Remote I/O

### YHLS Master Module

F3LH01-1N / F3LH02-1N



#### Fast, stress-free remote I/O with reduced wiring

YHLS (Yokogawa Hi-speed Link system) is a high-speed 1:N remote I/O communication system. It supports up to 63 connected slaves for processing data of up to 2,016 I/O points (1,008 inputs and 1,008 outputs) at high-speed scan of 243μs per 256 I/O points. Moreover, complex communication protocols are transparent to the programmer, simplifying system implementation.

#### Fast

- Up to 12Mbps. Scans 63 slave units in just 0.96ms.

#### Immune to Noise

- Adopts HLS protocol with excellent noise immunity
- Even more reliable when used with YHLS cables (KM80/KM81)

#### Open

- Open design rules allows customers to develop proprietary slave units

| Item                             | Specifications  |                               |
|----------------------------------|---|-------------------------------|
|                                  | F3LH01-1N   | F3LH02-1N                     |
| No. of systems                   | 1   | 2                             |
| Transmission mode                | 4-wire full duplex or 2-wire half duplex              |                               |
| Transmission format              | HLS compliant   |                               |
| Transmission rate                | 3Mbps, 6Mbps or 12Mbps                                |                               |
| Synchronization mode             | Bit synchronization                                   |                               |
| Error control                    | CRC-12  |                               |
| Transmission distance per system | 300m (at 3Mbps), 200m (at 6Mbps), or 100m (at 12Mbps) |                               |
| Connector type                   | European connector                                    |                               |
| No. of slaves per module         | 63  | 126                           |
| No. of I/O points per module     | 1,008 inputs<br>1,008 outputs                         | 2,016 inputs<br>2,016 outputs |

YHLS (YOKOGAWA Hi-speed Link System) adopts a HLS-compliant open protocol, enhanced to allow easy monitoring of transmission line quality during development and operation using RDY, ALM and LNK LED indicators.

### YHLS Slave Units

TAH Series

#### With hot swapping

These slave units offer 32 I/O points in a compact body comparable to 16-point slave units from other competitors, and are equipped with short-circuit protection for the I/O power supply and output circuits.



| Model   | Specifications   |
|---------|--|
| TAHWD32 | -3PAM 16 DC inputs (positive common), 24V DC, MIL 16 TR outputs (sink-type, with short-circuit protection), 24V DC 0.1A, MIL   |
|         | -3NBM 16 DC inputs (negative common), 24V DC, MIL 16 TR outputs (source-type, with short-circuit protection), 24V DC 0.1A, MIL |
| TAHXD16 | -3PEM 16 DC inputs (positive common), 24V DC, MIL  |
|         | -3NEM 16 DC inputs (negative common), 24V DC, MIL  |
| TAHYD16 | -3EAM 16 TR outputs (sink-type, with short-circuit protection), 24V DC 0.1A, MIL   |
|         | -3EBM 16 TR outputs (source-type, with short-circuit protection), 24V DC 0.1A, MIL   |

### YHLS Cables

KM80 / KM81

#### Two cable types for different purposes

These YHLS high-speed wire-saving cables have double shields against external noise, and can be used as generic serial cables for standard RS-422A/485 communications.

| Model               | Cable Length | Model | Cable Length           |      |      |
|---------------------|--------------|-------|------------------------|------|------|
| KM80 (Fixed cables) | -010         | 10m   | KM81 (Flexible cables) | -010 | 10m  |
|                     | -050         | 50m   |                        | -050 | 50m  |
|                     | -100         | 100m  |                        | -100 | 100m |
|                     | -200         | 200m  |                        | -200 | 200m |
|                     | -300         | 300m  |                        | -200 | 200m |

Usable with modules: F3LH01-1N, F3LH02-1N, F3LP32-0N, F3LR02-1W, F3LC11-2F, F3LC31-2F, F3LC51-2N, F3RZ91-0F



# Superior, Easy Temperature Control

## Superior temperature control with easy setup

Temperature Control and PID Modules

F3CU04-0S / F3CU04-1S



**Versatile control at high speed, accuracy and resolution**

Up to 144 loops

Sampling **0.1s** Accuracy **±0.1%** Resolution **0.1°C**

This module enables fine control at high speed, accuracy and resolution. Its built-in "SUPER" function suppresses overshooting using fuzzy theory to deliver improved manufacturing quality. Its superior functions and performance can be easily harnessed using its "dynamic auto-tuning" function or setup tool.

| Item                       | Specifications  |  |
|----------------------------|---|--|
|                            | F3CU04-0S   | F3CU04-1S  |
| No. of loops/channels      | 4 loops   |  |
| Isolation method           | Between input terminals and internal circuit: Isolation by photocouplers and transformers<br>Between input terminals: Independent circuits for different channels |  |
| Input type                 | Universal input (individual inputs configurable separately by software or collectively by hardware): 15 thermocouples, 9 RTDs, 2 DC mV ranges, and 4 DC V ranges  |  |
| Input sampling cycle       | 100ms for 2 channels or 200ms for 4 channels  |  |
| Input impedance            | 1MΩ or more   |  |
| Allowable signal impedance | 250Ω max. for thermocouple and DC mV, 100Ω max. for RTD (with same wire resistance), and 2kΩ max. for DC V  |  |
| Burnout detection function | Yes   |  |
| Output type                | Time proportioning PID (Open collector output)  | Yes (ON/OFF control, forward/reverse)  |
|                            | Continuous PID (4-20mA output)  | No Yes   |
| Control section            | Control function  | ON/OFF, PID, heating/cooling, setting output, dynamic auto-tuning, and "Super" |
|                            | Control cycle   | Same as input sampling cycle   |

### High Speed, High Accuracy, High Resolution

- Input sampling cycle: 100ms/2CH, 200ms/4CH
- Input accuracy: ±0.1% of F.S.
- Input resolution: 0.1°C (5-digit display)

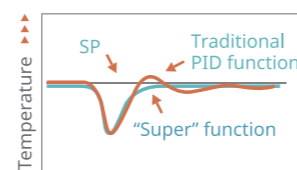
### Universal Input

A single module can be used to support a variety of inputs (thermocouple, RTD, DC mV and DC V), selectable for each channel. By configuring individual channels to separate inputs, it delivers high efficiency at low cost.

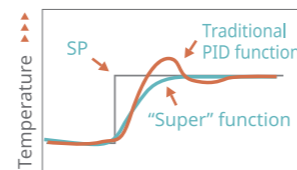
### Dynamic Auto-tuning Function

- With a user setting the minimum number of parameters (such as input/output range and control set point), this module automatically calculates the optimal PID parameters to simplify startup preparation, saving tuning effort and cost.
- It even recalculates the PID parameters automatically when there is a major change in the control condition (i.e. change in control set point) during operation.

### Overshoot Suppression Function SUPER



When a disturbance occurs



When a setting is changed



Temperature Monitoring Module

F3CX04-0N

**Easy temperature monitoring with superior cost-performance**

Up to 144 channels

- Input sampling cycle: 100ms/2CH, 200ms/4CH
- Input accuracy: ±0.1% of F.S.
- Input resolution: 0.1°C (5-digit display)
- Universal input  
Up to 144 channels (4 channels x 36 modules)

| Item                       | Specifications  |  |
|----------------------------|---|--|
|                            | F3CX04-0N   |  |
| No. of loops/channels      | 4 channels  |  |
| Isolation method           | Between input terminals and internal circuit: Isolation by photocouplers and transformers<br>Between input terminals: Independent circuits for different channels |  |
| Input type                 | Universal input (individual inputs configurable separately by software or collectively by hardware): 15 thermocouples, 9 RTDs, 2 DC mV ranges, and 4 DC V ranges  |  |
| Input sampling cycle       | 100ms for 2 channels or 200ms for 4 channels  |  |
| Input impedance            | 1MΩ or more   |  |
| Allowable signal impedance | 250Ω max. for thermocouple and DC mV, 100Ω max. for RTD (with same wire resistance), and 2kΩ max. for DC V  |  |
| Burnout detection function | Yes   |  |

ToolBox for Temperature Control and Monitoring Modules

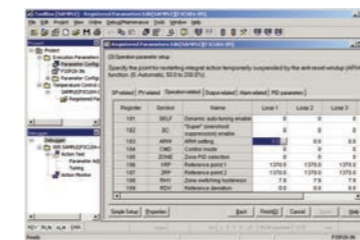
SF661-MCW



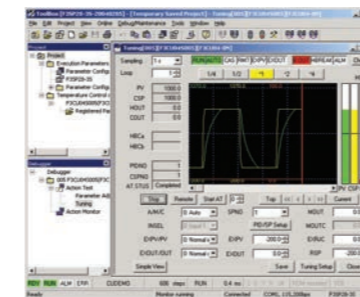
### Easy Setup of Operation Parameters

This software is a parameter setup tool for use with the FA-M3 Temperature Control and PID Modules and the Temperature Monitoring Module. It supports a range of functions from initial setup to action testing, and simplifies the tedious tuning process by enabling graphical display of monitored values.

### Detailed setup



### Tuning



### User-friendly setup screens

On-line help information on module parameters simplifies parameter setup. Setup screens can be customized with the required parameters displayed in the appropriate order to match user operation.

### Powerful debugging and data logging

Display of preset values, action monitoring and display of error information are available during action testing. Input field data can be logged, and exported (in CSV format) as external data to be used in subsequent reporting, analysis or processing.

### Integrated development environment

ToolBox provides a convenient, integrated development environment, which does not require a user to run each tool separately when using the ToolBox for Temperature Control and Monitoring Module (SF661-MCW) concurrently with the ToolBox for Positioning Modules (SF662-MCW/SF663-MCW).

### Concurrent use of ToolBox and FA-M3 Programming Tool WideField3

The ToolBox software can be executed concurrently with WideField3, and even allows concurrent editing and communications using both programs.

\* Use ToolBox R6.01 or a later version with F3SP22, F3SP71 and F3SP76 sequence CPU modules.

# Drastically Reduced Tact Time

## Versatile positioning control using efficient setup tool

### Positioning Module (with multi-channel pulse output)

F3YP22-0P / F3YP24-0P / F3YP28-0P



#### 8-axis max. for single module, Pursuit higher speed and shorter control period

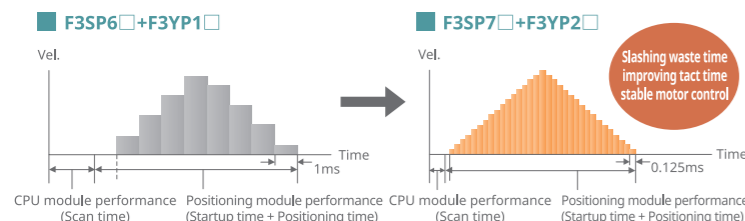
This positioning module enables up to 8 axes control by one module and reduces the cost per an axis.

It can be used to configure positioning systems for up to 128 axes, by using 16 modules.

Various trigger functions enable quick and accurate startup and stop from external devices with preset destination and speed.

- Short startup time of 40μs min. for 1 axis, 90μs min. for 4 axes and 150μs min. for 8axes. A trigger start allows 1μs min. enables to start operation faster.
- A short control cycle of 0.125ms for 8 axes allows smoother positioning commands and enables faster movement on the work. In addition, response for changing variables and positioning status becomes quicker.
- Max. 7.996Mpps output of high-speed positioning command provides comfortable margin for driving linear, DD, and other high-speed, high-precision motors.
- Built-in pulse counter can accept max 8Mpps for detecting the position of external devices, like the position on an index table or the travel distance of a conveyor, and allows faster and more precise positioning control.

| Item                    | Specifications  |  |           |   |
|-------------------------|---|--|-----------|---|
|                         | F3YP22-0P   | F3YP24-0P  | F3YP28-0P |   |
| Control                 | No. of axes   | 2  | 4         | 8 |
|                         | Control method  | Open-loop control with positioning command pulse output  |           |   |
|                         | Pulse output method   | RS-422A compliant differential line driver (ISL32172E equivalent)<br>Pulse type selectable for each axis: CW/CCW pulse, travel/direction pulse, and phase A/B pulse  |           |   |
|                         | Output pulse rates  | 7,996,000 (pulse/s)max. - Using a servomotor<br>1,999,000 (pulse/s) max. - Using a stepper motor   |           |   |
|                         | Control period  | 0.125ms  |           |   |
| External contact input  | 4 inputs per axis (origin input, forward and reverse limit inputs, and Z-phase input) |  |           |   |
| External contact output | 1 output per axis (deviation pulse clear signal)                                      |  |           |   |
| Positioning functions   | Control unit  | pulse  |           |   |
|                         | Control mode  | Position control (PTP control, multi-axis linear interpolation), speed control, and speed control to position control switchover   |           |   |
|                         | Operation method  | Direct operation, position data record operation (10 data/axis)  |           |   |
|                         | Command position  | Absolute/incremental positioning command, -2,147,483,648 to 2,147,483,647 (pulse/s)  |           |   |
|                         | Command speed   | 1 to 7,996,000 (pulse/s) - Using a servomotor<br>1 to 1,999,000 (pulse/s) - Using a stepper motor  |           |   |
|                         | Acceleration/deceleration system  | Automatic trapezoidal acceleration/deceleration (startup speed programmable)<br>Automatic S-shape acceleration/deceleration (startup speed fixed)  |           |   |
|                         | Acceleration/deceleration time  | 0 to 32,767(ms) (configurable for acceleration and deceleration separately)  |           |   |
|                         | Origin search   | Two types of automatic origin search<br>Manual origin search (user-definable using a combination of external contact inputs)   |           |   |
|                         | Manual control  | Jog and manual pulse generator mode  |           |   |
|                         | Startup time  | 0.04ms for 1 axis, 0.09ms for 4 axes, 0.15ms for 8 axes  |           |   |
| Counter                 | No. of channels   | 1 channel  |           |   |
|                         | Pulse input method  | Pulse type selectable: CW/CCW pulse, travel/direction pulse, and phase A/B pulse   |           |   |
|                         | Input pulse rate  | 8,000,000 (pulse/s) max. (x4)  |           |   |
|                         | Operation mode  | Linear counter, ring counter   |           |   |
|                         | Counter enable functions  | Counter enable function, counter preset function, counter coincidence detection function, cam-operated switch function, counter latch function, speed measurement function, positioning start/stop by an external trigger or counter coincidence |           |   |
|                         | Counter Z-phase input   | 1 input (latch input, present input, and so on can be assigned)  |           |   |
|                         | Counter external contact input  | 3 inputs (latch input, present input, enable input, trigger condition of the positioning function, and so on can be assigned)  |           |   |
|                         | Counter external contact output   | 2 outputs (counter coincidence output, cam-operated switch output, and so on can be assigned)  |           |   |
|                         | Data backup   | Flash ROM (100,000 times rewritable)   |           |   |



### ToolBox for Positioning Modules (for F3NC32/34)

SF662-MCW

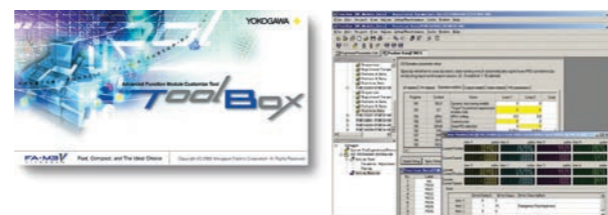
### ToolBox for Positioning Modules (for F3YP22/24/28)

SF663-MCW

### Total development support from configuration through maintenance

This Window-based software tool for configuring positioning modules (F3NC32-0N and F3NC34-0N) and positioning modules (F3YP22-0P/F3YP24-0P/F3YP28-0P) can be used to set up parameters, as well as perform action test and monitoring. With ToolBox, configuration and debugging of positioning modules becomes an easy job.

\* Use ToolBox R4.01 or a later version with F3SP22, F3SP71 and F3SP76 sequence CPU modules.



### Positioning Module (with MECHATROLINK-III Interface)

F3NC97-0N

### Positioning Module (with MECHATROLINK-II Interface)

F3NC96-0N



#### With the latest open motion-control network interface

This positioning module supports MECHATROLINK-III<sup>\*1\*</sup>, the latest Ethernet-based, high-performance, advanced, open field network standard published by the MECHATROLINK Members Association. It is the top choice for configuring a system involving many controlled axes.

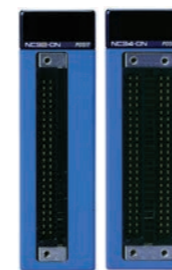
- Positioning control for up to 15 axes from a single slot
- Easy connection using connectors, saving wiring between motors and controllers
- Fast transmission at 100 Mbps<sup>\*2</sup> transmission rate and 0.25ms cycle time for 4 axes<sup>\*2</sup> enables a shorter tact time and higher productivity.
- Up to 8 monitor data per axis<sup>\*2</sup> can be read simultaneously for better monitoring of external devices.
- In addition to AC servo motors, stepping motors, I/O devices and inverters from more manufacturers will be supported in future.

\*1: MECHATROLINK is a trademark of the MECHATROLINK Members Association.  
\*2: Available with F3NC97-0N only.



### Positioning Module (with Pulse Output)

F3NC32-0N / F3NC34-0N

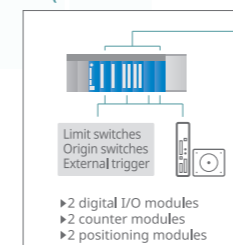


#### For fast, accurate, high-resolution and versatile position control

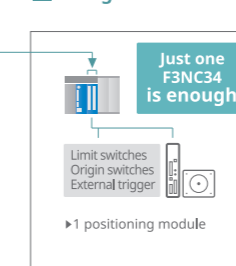
This positioning module is equipped with a pulse counter for each axis. It is amply powered to control high-speed, high-precision and high resolution devices and motors.

- Output pulse rate of 5Mpps max. gives ample power for driving direct-drive and linear motors.
- Its range of positioning control functions enables a much shorter tact time, higher productivity and better product quality.
- Using its built-in pulse counters and contact I/O, wiring is simpler and less modules are needed.

#### Using older positioning modules (for 4-axis motion control)



#### Using F3NC34



| Item                           | Specifications   |  |
|--------------------------------|--|--|
|                                | F3NC97-0N  | F3NC96-0N  |
| Interface                      | MECHATROLINK-III compliant   | MECHATROLINK-II compliant  |
| Physical layer                 | Ethernet   | RS-485 equivalent  |
| Transmission rate              | 100Mbps  | 10Mbps   |
| Cycle time / no. of stations   | 0.25ms for 4 axes<br>0.5ms for 8 axes<br>1.0ms for 15 axes (multislave function compliant <sup>*3</sup> )  | 1.0ms for 8 axes<br>2.0ms for 15 axes  |
|                                | Transmission bytes   | 16, 32, 48, or 64 bytes (intermixing allowed)  |
| Communications method          | Cyclic communication   | Master/slave synchronous   |
| Network topology               | Cascade or star  | Bus  |
| Transmission media             | Ethernet STP Cat5e (dedicated cable)   | 2-wire shielded twisted pair cable (dedicated cable)   |
| Max. transmission distance     | 100m (between stations)  | 50m (total length)   |
| Min. distance between stations | 0.2m   | 0.5m   |
| Compatible slave devices       | - Standard servo profile<br>- Standard I/O profile <sup>*4</sup><br>- Standard stepping motor drivers profile <sup>*3</sup><br>- Standard inverter profile <sup>*3</sup> | - Communication commands for servo drives<br>- Communication commands for stepping motor drives  |
|                                | Position reference   | -2,147,483,648 to 2,147,483,647 (reference unit)   |
| Positioning functions          | Functions  | - Independent axis movement using MECHATROLINK-II/III commands (availability depends on connected equipment and supported MECHATROLINK-II/III commands)<br>- Linear interpolation movement (simultaneous starting and stopping), speed/target position change during motion                                    |
|                                | Others   | - Status monitoring of external devices (target position, current position, speed, and torque)<br>- Reading and writing parameters of external devices<br>- Inverter control by standard inverter profile commands <sup>*3,*5</sup><br>- External device I/O using standard I/O profile commands <sup>*5</sup> |

\*3: Supported from the revision REV: 01:□□ of the module  
\*4: Synchronous communication is supported and commands are added from the revision REV: 01:□□ of the module  
\*5: For F3NC97-0N only

| Item                    | Specifications   |  |   |
|-------------------------|--|--|---|
|                         | F3NC32-0N  | F3NC34-0N  |   |
| Control                 | No. of axes  | 2  | 4 |
|                         | Control method   | Open-loop control using position reference pulse output  |   |
|                         | Output pulse type  | RS-422A compliant differential line driver; 5Mpps for servomotors, 1Mpps for stepping motors<br>Pulse type selectable for each axis: CW/CCW pulse, travel/direction pulse, and phase A/phase B pulse           |   |
| Counter                 | No. of channels  | 2  | 4 |
|                         | Input pulse type   | Incremental encoder (phase A/B), absolute encoder; 5Mpps input pulse rate (after 4x multiplication)  |   |
| External contact input  | 6 inputs per axis (origin, forward limit, reverse limit, driver alarm input, external trigger, general-purpose input); emergency stop                |  |   |
| External contact output | 3 outputs per axis (one deviation pulse clear signal and two general-purpose outputs), and 1 SEN signal per axis                                     |  |   |
| Positioning functions   | Units of measurement   | mm, degrees, and pulses  |   |
|                         | Control modes  | Position control, speed control, position-control ↔ speed-control switchover   |   |
|                         | Interpolation modes  | 2-axis linear interpolation   2-, 3-, and 4-axis linear interpolation<br>2-axis circular interpolation   2-axis circular and helical interpolation   |   |
|                         | Operation modes  | Pattern operation and direct operation   |   |
|                         | Pattern operation  | PTP movement, CP normal movement, CP pass-by movement, and CP pass-through movement;<br>No. of action pattern records: 2,000 max. (500 actions x 4 patterns); No. of position data records: 2,000 max per axis |   |
|                         | Position reference   | Absolute/incremental position reference<br>-2,147,483,648 to 2,147,483,647 (pulses)  |   |
|                         | Speed reference  | 1 to 5,000,000pps  |   |
|                         | ACC/DCC curve  | Automatic trapezoidal acceleration/deceleration<br>Automatic S-shape acceleration/deceleration   |   |
|                         | ACC/DCC time   | 0 to 32,767ms (configurable independently for acceleration and deceleration)   |   |
|                         | Others   | Change in target position during movement<br>Change in specified speed during movement   |   |
| Origin search           | Two types of automatic origin search; Manual origin search (any combination of external contact inputs may be used)                                  |  |   |
| Manual operation        | Jog operation and manual pulse generator mode  |  |   |
| Other functions         | Electronic gear, teaching, current position setup, M code output, override, software limit switch, Counter coincidence or zone coincidence detection |  |   |
| Data backup             | Flash ROM (100,000 times rewritable)   |  |   |

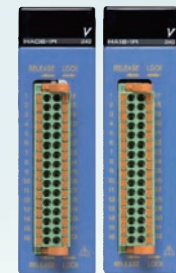


# A Wide Selection of Modules

## To suit every application need

### High-speed data acquisition module

F3HA06-1R / F3HA12-1R



#### Stable, fast data sampling, without affecting scan time

This analog module enables large data acquisition and analysis by pursuit of high-speed and high-accuracy. It contributes to optimize for customers instruments.

#### High-speed, high-resolution

5 $\mu$ s conversion period coupled with 16bit ADC enables highly accurate tracing of signal changes. About 50 $\mu$ s response allows monitoring current values even during data acquisition.

#### Long memory

2M words of large data buffer size. Sampling period is configurable as a multiple(1 to 4,000) of the A/D conversion period.

#### Concurrent, synchronous operation

A/D conversion can be synchronized with an internal counter or external signal. Concurrent A/D conversion for up to 12 channels: 5 $\mu$ s for one to 12 channels. Supports A/D conversion associated with the encoder input for position or angular information.

#### Various functions

Built-in FFT function calculates for up to 16,384 data points. Fast, stable data sampling according to configuration from the CPU module. Enables signal range restriction by combining low-pass and high-pass filter.

| Item                          | Specifications  |           |
|-------------------------------|---|-----------|
|                               | F3HA06-1R   | F3HA12-1R |
| No. of inputs                 | 6   | 12        |
| Input signal range            | -10 to 10V (-11 to 11V, default), 0 to 10V (-0.5 to 10.5V)<br>1 to 5V (-0.25 to 5.25V), -5 to 5V (-5.5 to 5.5V),<br>-2.5 to 2.5V (-2.75 to 2.75V)   |           |
| Isolation                     | Analog input terminals/internal circuit: Isolated<br>Analog input channel/analog input channel: Not isolated<br>Auxiliary input terminals/internal circuit: Isolated<br>Auxiliary input terminal/auxiliary input terminal: Not isolated<br>Analog input terminal/auxiliary input terminal: Isolated |           |
| Resolution (16 bit ADC)       | Approx. 1/58,000, Approx. 0.35mV (-10 to 10V range)<br>Approx. 1/29,000, Approx. 0.35mV (0 to 10V range)<br>Approx. 1/23,000, Approx. 0.18mV (1 to 5V range)<br>Approx. 1/58,000, Approx. 0.18mV (-5 to 5V range)<br>Approx. 1/29,000, Approx. 0.18mV (-2.5 to 2.5V range)                          |           |
| Overall accuracy              | $\pm 0.1\%$ of full scale (23 $\pm 2^\circ\text{C}$ ) $\pm 0.1\%$ of full scale /K,<br>$\pm 0.3\%$ of full scale (0 to 55 $^\circ\text{C}$ )  |           |
| A/D conversion operation mode | Periodic sampling: 5 $\mu$ s period<br>External signal synchronized: interval 5 $\mu$ s min, response 0.2 $\mu$ s max.<br>Counter synchronized: interval 5 $\mu$ s min, response 0.2 $\mu$ s max.   |           |
| Input response time           | Approx. 50 $\mu$ s max. (at 0-to-1 V step input)<br>(analog circuit stabilization time + conversion time + calculation time)  |           |
| Data buffer                   | 1M words max. double buffer (2M words max.)   |           |
| Data buffer sampling period   | Sampling period x n, where n is a natural number from 1 to 4,000  |           |
| Scaling                       | Configurable within -30,000 to 30,000<br>using scale high limit and scale low limit   |           |
| Auxiliary input filter        | Filtering of counter and general input signals  |           |
| Post-data processing          | Averaging (over 512 frames max.)<br>FFT (16,384 data points max., averaging over 16 frames max.)  |           |

|   |  |
|---|--|
| <b>Conversion period</b><br>5 $\mu$ s (200kS/s) | <b>Data buffer</b><br>2M words   |
| <b>A/D conversion</b><br>Counter-synchronized   | <b>for up to</b><br>16,384 data points<br><b>Built-in FFT function</b> |

### FA Link H2 Module

F3LP32-0N



#### Easy PLC expansion and distribution using twisted-pair cables

This interface module uses shielded twisted-pair cables to achieve maximum transmission rate of 1.25Mbps and is ideal for connecting machines.

| Item                  | Specifications   |
|-----------------------|--|
| No. of stations       | Max.32   |
| Link relays           | 2,048  |
| Link registers        | 2,048  |
| Communication method  | Token bus  |
| Transmission media    | Shielded twisted-pair cable<br>(KM80/KM81 recommended) |
| Transmission distance | 1km/500m/250m/100m                                     |
| Transmission rate     | 125k/250k/625k/1.25Mbps                                |

### Fiber-optic FA Bus Type 2 Module

F3LR02-0N

### FA Bus Type 2 Module

F3LR02-1W



#### Establishes instantaneous remote I/O

These interface modules can be used to build a remote I/O system on a (fiber-optic or electric wire) FA bus. The high transmission rate of 10 Mbps eliminates any concerns about I/O refresh time in ladder programming. Moreover, star, daisy-chain and loop connections are all supported, allowing for flexible configuration.

| Item                  | Specifications                                    |   |
|-----------------------|---|---|
|                       | F3LR02-0N   | F3LR02-1W   |
| Transmission method   | Star, daisy chain, loop                           |   |
| Transmission media    | 2-wire fiber-optic cable                          | two-pair (4-wire) shielded cable<br>(KM80/KM81 recommended) |
| Transmission distance | Total distance: 1.4km max.<br>(with 3 stations)*1 | 80m max.<br>(for loop configuration)                        |
| Transmission rate     | 10Mbps  |   |

\*1 It is necessary to confirm with Sumitomo Electric Industries, Ltd about the production of cables that are compliant with the module specifications.

### Analog Output Module

F3DA04-6R / F3DA08-5R

### Analog Input Module

F3AD04-5R / F3AD08-□R



#### Fast, accurate, advanced conversion with excellent noise immunity

The analog output modules feature built-in 16-bit high-resolution D/A conversion with fast conversion speed of 2 $\mu$ s per channel and real-time output response of 2 $\mu$ s + 2 $\mu$ s x (number of channels to be updated). Moreover, it supports synchronous update for up to 8 output channels.

Real-time output response of 4 $\mu$ s per channel

Synchronous update for up to 8 output channels



The analog input modules feature built-in 16-bit high-resolution A/D converter including standard 12-bit models. Conversion speed is user-configurable from 50 $\mu$ s to 100ms to suit different applications.

| Item                      | Specifications   |   |
|---------------------------|--|---|
|                           | F3DA04-6R  | F3DA08-5R   |
| No. of outputs            | 4  | 8   |
| Output signal range       | Voltage output: -10 to 10V (-11 to 11V) 0 to 10V (-0.5 to 10.5V)<br>0 to 5V (-0.25 to 5.25V) 1 to 5V (0.1 to 5.25V)<br>Current output: 4 to 20mA (1.25 to 21mA) 0 to 20mA (-1 to 21mA)<br>-20 to 20mA (-21 to 21mA)  | Voltage output: -10 to 10V (-11 to 11V) 0 to 10V (-0.5 to 10.5V)<br>0 to 5V (-0.25 to 5.25V) 1 to 5V (0.1 to 5.25V)                 |
| Isolation                 | Between output terminals and internal circuitry: Isolated (capacitance coupling)<br>Between output terminals and external power supply: Not isolated, common negative  |   |
| Allowable load resistance | Voltage output: 1k $\Omega$ min. (for -10 to 10V or 0 to 10V range)<br>500 $\Omega$ min. (for 0 to 5V or 1 to 5V range)<br>Current output: 600 $\Omega$ min.   | Voltage output: 1k $\Omega$ min. (for -10 to 10V or 0 to 10V range)<br>500 $\Omega$ min. (for 0 to 5V or 1 to 5V range).            |
| Resolution(16-bit DAC)    | Voltage output: $\approx 0.5\text{mV}$ (for -10 to 10V or 0 to 10V range)<br>$\approx 0.2\text{mV}$ (for 0 to 5V or 1 to 5V range).<br>Current output: $\approx 0.5\mu\text{A}$ (for 4 to 20mA range)<br>$\approx 1\mu\text{A}$ (for 0 to 20mA or -20 to 20mA range) | Voltage output: $\approx 0.5\text{mV}$ (for -10 to 10V or 0 to 10V range)<br>$\approx 0.2\text{mV}$ (for 0 to 5V or 1 to 5V range). |
| Overall accuracy          | Voltage output: $\pm 0.1\%$ of FS (23 $\pm 2^\circ\text{C}$ ) $\pm 0.3\%$ of FS (0 to 55 $^\circ\text{C}$ )<br>Current output: $\pm 0.2\%$ of FS (23 $\pm 2^\circ\text{C}$ ) $\pm 0.3\%$ of FS (0 to 55 $^\circ\text{C}$ )   | Voltage output: $\pm 0.1\%$ of FS (23 $\pm 2^\circ\text{C}$ ) $\pm 0.3\%$ of FS (0 to 55 $^\circ\text{C}$ )                         |
| Output update time *1     | 2 $\mu$ s + 2 $\mu$ s x (number of channels to be updated)   |   |
| Synchronous output *2     | DAC of all active channels of the same module can be updated synchronously   |   |
| Output response time      | Voltage output: $\approx 20\mu\text{s}$ (for -10 to 10V range with 2k $\Omega$ load)<br>Current output: $\approx 10\mu\text{s}$ (for 4 to 20mA range with 250 $\Omega$ load)   | Voltage output: $\approx 20\mu\text{s}$ (for -10 to 10V range with 2k $\Omega$ load)  |
| Scaling                   | Output signal range can be set to any digital range within -30,000 and 30,000  |   |
| External power supply     | Rated voltage: 24V DC; Allowable voltage range: 19.2 to 30V DC Current consumption: 200mA (inrush current: 1A)   |   |

\*1: The given output update time is applicable under certain conditions.

\*2: The synchronous output update period depends on the number of channels used and the application.

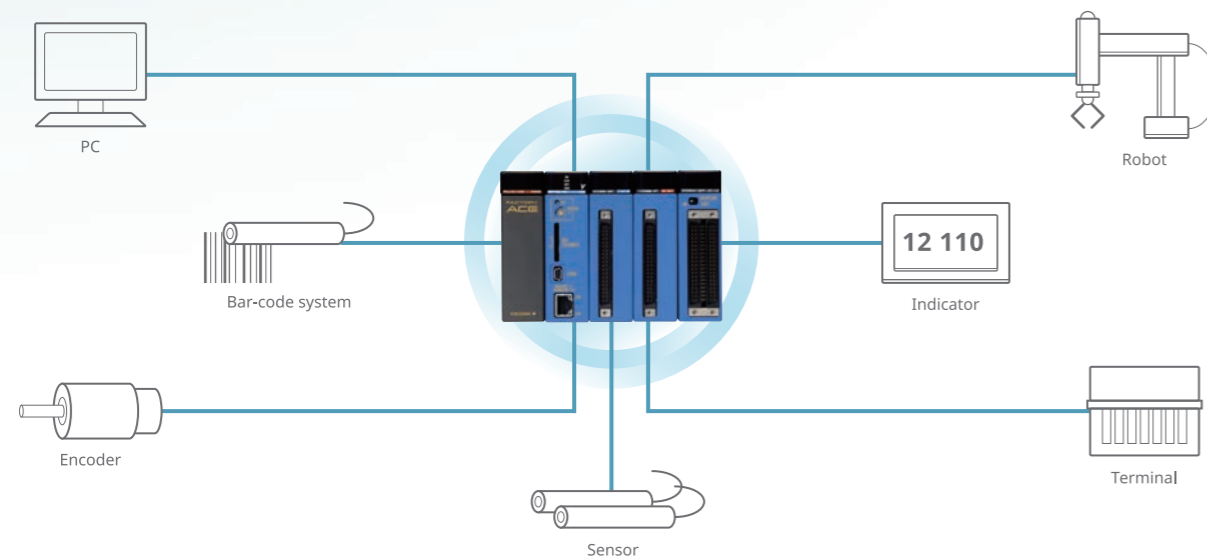
| Item                 | Specifications   |   |  |   |
|----------------------|--|---|--|---|
|                      | F3AD04-5R  | F3AD08-4R   | F3AD08-5R  | F3AD08-6R   |
| No. of input         | 4  | 8   |  |   |
| Input signal range   | Voltage signal only<br>0 to 5V DC(-0.25 to 5.25V DC)<br>1 to 5V DC(-0.25 to 5.25V DC)<br>-10 to 10V DC(-11.0 to 11.0V DC)<br>0 to 10V DC(-0.5 to 10.5V DC) | Current signal only<br>0 to 20mA DC<br>(-1.0 to 21.0mA DC)<br>4 to 20mA DC<br>(-1.0 to 21.0mA DC) | Voltage signal only<br>0 to 5V DC(-0.25 to 5.25V DC)<br>1 to 5V DC(-0.25 to 5.25V DC)<br>-10 to 10V DC(-11.0 to 11.0V DC)<br>0 to 10V DC(-0.5 to 10.5V DC) | Voltage signal or current signal<br>0 to 5V DC(-0.25 to 5.25V DC)<br>1 to 5V DC(-0.25 to 5.25V DC)<br>-10 to 10V DC(-11.0 to 11.0V DC)<br>0 to 10V DC(-0.5 to 10.5V DC)<br>0 to 20mA DC(-1.0 to 21.0mA DC)<br>4 to 20mA DC(-1.0 to 21.0mA DC) |
| Isolation method     | Across input terminals and internal circuit: Photocoupler isolation<br>Across input terminals: Not isolated  |   |  |   |
| Resolution(16bitA/D) | 0.4mV(0 to 5V/1 to 5V DC/<br>0 to 10V DC/-10 to 10V DC)  | 1.6 $\mu\text{A}$<br>(0 to 20mA DC/4 to 20mA DC)  | 0.4mV(0 to 5V/1 to 5V DC/0 to 10V<br>DC/-10 to 10V DC)   | 1.6 $\mu\text{A}$<br>(0 to 20mA DC/4 to 20mA DC)  |
| Overall accuracy     | $\pm 0.1\%$ of FS (23 $\pm 2^\circ\text{C}$ ), $\pm 0.2\%$ of FS (0 to 55 $^\circ\text{C}$ )   |   |  |   |
| Conversion period    | 50 $\mu$ s/100 $\mu$ s/250 $\mu$ s/500 $\mu$ s/1ms/16.6ms/20ms/100ms per channel Configurable on module basis  |   |  |   |
| Scaling              | Upper and lower limit values can be set to any value between -30,000 and 30,000  |   |  |   |
| Offset               | Offset value can be set to any value between -5,000 and 5,000  |   |  |   |
| Filter               | Channels can be enabled or disabled individually   |   |  |   |
| Hold data            | Supports recording of peak values and trough values  |   |  |   |
| Self diagnosis       | Hardware self-diagnosis during operation Over-range input detection  |   |  |   |

# Open Partnership

## FA-M3 design rules made open through I/O Open

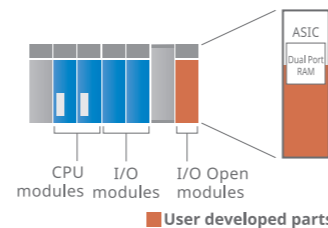
As a customer, would you like to create your own dedicated module?

"I would like to make a direct bus connection to an external image processing controller." "I would like to incorporate an external controller inside our machine to make space." "I would like an economically efficient communication interface with excellent performance." "My cost has ballooned with ever faster obsolescence of board components. What can I do?" The answers to your problems can be found in Yokogawa's new FA-M3 module development environment, named I/O Open. With I/O Open, customers can now build their own FA-M3 compatible user I/O modules to improve performance and functionality of their devices at dramatically reduced total cost of ownership (TCO).



### FA-M3 Design Rules Made Open

The Open Partnership program empowers customers to develop their own I/O modules. By implementing proprietary know-how in the form of an FA-M3-compatible user I/O module, users can achieve increased package density and performance. Moreover, complex data transfer between the CPU module and I/O modules is handled by an ASIC interface, which simply requires data to be written into a Dual Port RAM. Special parts required for module development such as ASIC, module casing and connectors can all be purchased from Yokogawa so customers only need to focus on the design of a printed circuit board.



### FA-M3 I/O Open

#### Seamless System Integration

An FA-M3 compatible user module, which is seamlessly integrated with the FA-M3 system, can demonstrate its unique functionality and also easily exchange data with high-level equipment and other FA-M3 systems through Ethernet.

#### Low Cost

If the functions of an external controller are built into an FA-M3 user I/O module, it will not only avoid unnecessary investments and space, but also minimize software development effort and yield maximum cost savings.

#### Flexibility

As an example, consider developing an FA-M3 compatible user I/O module incorporating a program for communicating with an external controller. This approach improves total communication performance. No communication programs for the CPU module need to be written so modification of individual devices is easier.

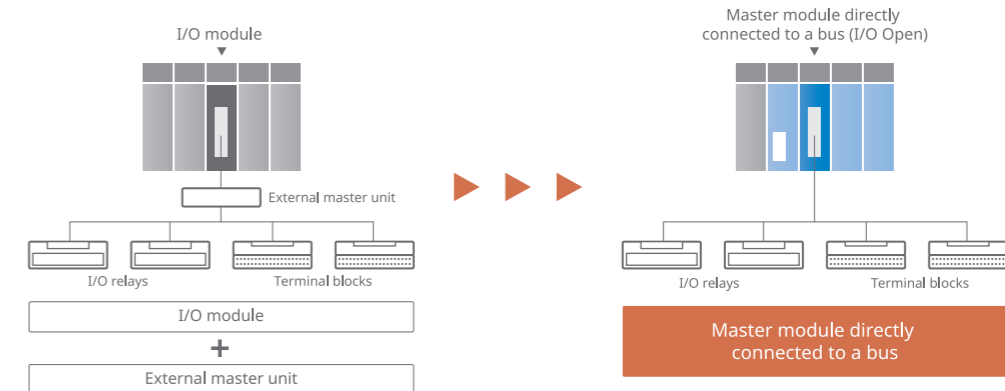
#### Simple System Configuration

An FA-M3 user I/O module can achieve both control and data processing with no need to purchase extra devices or reconfigure a new system, resulting in a simpler system configuration.

### Application Examples

#### Reduced Wiring

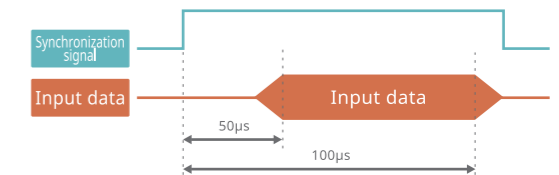
- By minimizing superfluous units, a simpler system configuration, higher speed and lower cost can be achieved.
- By eliminating connector parts, higher reliability is ensured.



#### Implementing I/O signal processing not achievable with standard I/O modules

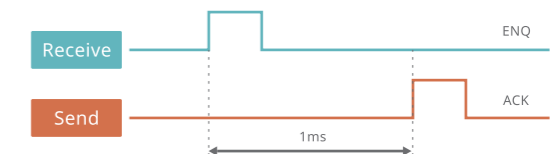
##### Control signal-synchronized data input

A dedicated module is created to acquire input data starting from 50µs until 100µs after the rising edge of a synchronization signal.



##### High-speed handshake

A dedicated communication module is created to return an ACK signal within 1ms after receiving an ENQ signal without going through the sequence CPU module.



#### Incorporating special sensor controller functions in a special module

- A dedicated module can be created for use with a high-resolution sensor to enable accurate and fast reading of data and high-accuracy positioning control for a diverse range of industrial machinery.



#### I/O Open implementation examples

- |  |                                |                                   |
|--|--------------------------------|-----------------------------------|
| - Wire saving system   | - Ice thermal storage system   | - Small-power generation system   |
| - Position sensor input system                                 | - Automatic vending machine    | - Building airconditioning system |
| - Semi-conductor equipment (chiller control, cleaner, handler) | - Components moulder/insertion | - Generator control system        |
| - Electronic weigher   | - Molding machine controller   | - F/V convertor module            |
| - Electron accelerator   | - Car washing machine          | - Governor control                |
|  | - Audio communication system   | - AGV                             |

Note: Only some examples are listed above.



# Peripherals

## For use with FA-M3

### Connector Terminal Block

TA50-0N / TA50-2N

#### A wide range of connector terminal blocks

##### Connector terminal blocks

- 40-point plug-type terminal block  
Compatible with 32-point and 64-point input/output modules and positioning modules
- Uses a connector terminal block cable for connection between the I/O module and connector terminal block, leading to space savings and reduced wiring within a distribution panel.
- No need for soldering during wiring of connector terminal block.



\* To connect to an I/O module using KM55-□□□ cable.

| Item                                | Specifications                                  |   |
|-------------------------------------|---|---|
|                                     | TA50-0N   | TA50-2N                                       |
| No. of I/O points                   | 40  |   |
| Rated voltage                       | 5 to 24V DC                                     |   |
| Operating voltage range             | 4.5 to 26.4V DC                                 |   |
| Maximum current                     | 0.5A DC/point                                   |   |
| Compatible cable                    | 2mm <sup>2</sup> max.                           | 1.25mm <sup>2</sup> max.                      |
| Terminal block screw                | M3.5  | M3  |
| Compatible terminal                 | Crimp-on terminal with max. diameter of 8mm     | Crimp-on terminal with max. diameter of 5.8mm |
| Connector                           | HIF3BA-40PA-2.54DSA (compliant to MIL standard) |   |
| Mounting                            | 35mm wide DIN rail or screws                    |   |
| Mounting screw (When screw-mounted) | M4-size screws (2 places)                       |   |
| Color                               | Black   | Gray  |
| Weight                              | 300g  | 162g  |

\* This connector terminal block cannot be used with F3YP22, F3YP24, F3YP28, F3NC32 and F3NC34.

### Terminal Block Unit

TA40-0N

- Ultra-thin connector enables space saving with compact panel design.
- Connects directly to input/output module with no need of cables, leading to cost savings.
- Use of European type terminal block eliminates the hassle of soldering or crimping.
- Can be secured directly to an I/O module using screws to ensure reliable connection.



| Item                    | Specifications                          |
|-------------------------|---|
| No. of I/O points       | 40                                      |
| Rated voltage           | 5 to 24V DC                             |
| Operating voltage range | 4.5 to 26.4V DC                         |
| Maximum current         | 0.5A DC/point                           |
| Compatible cable        | AWG23-28 (0.08 to 0.26mm <sup>2</sup> ) |
| Terminal block screw    | Slotted M2-size screw                   |
| Mounting screw          | Slotted M2.6-size screw                 |
| Color                   | Black                                   |
| Weight                  | 50g                                     |

\* This terminal block unit cannot be used with F3YP22, F3YP24, F3YP28, F3NC32 and F3NC34.

### Blank Module

F3BL00-0N

#### Installs in an empty slot for improved appearance

- Installing a blank module in an empty slot of a base module or a slot reserved for future use improves appearance and prevents collection of dust on the base module and other modules.



### Cables for Programming Tools

KM13-1S

#### Connects directly to USB port on PC

- Cable for connecting programming port of sequence CPU (F3SP22) to USB port of PC.

\* Download the latest driver software from FA-M3's website for free!



### Input Simulator Switch

S9307UF

#### Handy tool for program debugging

- This is a simulator switch for 32-point input terminals compatible with F3XD32-□F, F3XD64-□F and F3WD64-□□.

\* Only one switch can be installed on a module.



### Fiber-optic Cables

KM60 / KM61 / KM62 / KM65 / KM69

#### Cables for connecting fiber-optic FA bus modules ( for F3LR0□ )

| Fiber-optic cords for wiring inside panel enclosure | Fiber-optic cables for indoor wiring            | Fiber-optic cables for outdoor wiring               |
|---|---|---|
| KM60-S06 (0.6m)                                     | Optical connectors requiring bonding & grinding | KM62-100 (100m)                                     |
| KM60-001 (1m)                                       | KM61-010 (10m)                                  | KM69-□□□ flame-retardant cable (equivalent of VW-1) |
| KM60-003 (3m)                                       | KM61-100 (100m)                                 |   |
|   | Optical connectors requiring crimping & cutting |   |
|   | KM65-001 (1m) KM65-010 (10m)                    |   |
|   | KM65-003 (3m) KM65-020 (20m)                    |   |
|   | KM65-005 (5m)                                   |   |

### Performance Specifications/Ladder Sequence Devices

| Item   | Specifications  |   |  |  |
|--|---|---|--|--|
|  | F3SP22-0S   | F3SP71-4S   | F3SP76-7S  |  |
| Control method                                 | Repeating operation (by stored program)   |   |  |  |
| I/O control method                             | Refresh method / Direct I/O command   |   |  |  |
| Programming language                           | Structured-ladder language, object ladder language, mnemonic language   |   |  |  |
| No. of I/O points                              | Max. 4,096 points   |   | Max. 8,192 points (including remote I/O)   |  |
| Program size(ROM resident allowed)             | Max. 10K steps  | Max. 60K steps  | Max. 260K steps  |  |
| No. of program blocks                          | Max. 1,024  | Max. 1,024 (program blocks & macro instructions combined: max.1,280)  |  |  |
| No. of instructions                            | Basic   | 37 types  | 40 types   |  |
|  | Application   | 324 types   | 445 types  |  |
| Instruction execution time                     | Basic   | 0.045 to 0.18μs/instruction   |  |  |
|  | Application   | 0.18μs/instruction or longer  |  |  |
| Monitored scan time                            | 10 to 200ms (configurable in units of 1ms)  |   |  |  |
| Power-on or power recovery after power failure | Auto start, auto restart (automatic logging of power ON/OFF and momentary power failure events)   |   |  |  |
| Other functions                                | <ul style="list-style-type: none"> <li>- Sensor control function (scan time 200μs to 25ms)</li> <li>- Configuration (device capacities, data lock-up range at power failure, error-time output, etc.)</li> <li>- Constant scan (1 to 190ms, settable on 0.1ms basis)</li> <li>- Debug function (forced set/reset, online edit etc.)</li> <li>- Error log (64 items), user log</li> <li>- Date/clock function (year/month/date/hour/minute/second/day)</li> <li>- Program protection</li> <li>- Writing program/data to ROM</li> <li>- Sampling trace function</li> <li>- Personal computer link function (transmission rate 115Kbps)</li> </ul> | <ul style="list-style-type: none"> <li>- Sensor control function (scan time 100μs to 25ms)</li> <li>- Configuration (device capacities, error-time output, etc.)</li> <li>- Constant scan (0.1 to 190ms, settable on 0.1ms basis)</li> <li>- Debug function (forced set/reset, online edit etc.)</li> <li>- Error log, user log</li> <li>- Operation log</li> <li>- Date/clock function (year/month/date/hour/minute/second/day)</li> <li>- Personal computer link (Ethernet port only)</li> <li>- Program protection</li> <li>- CPU properties (transmission settings, etc.)</li> <li>- Constant definition</li> <li>- Smart access</li> <li>- Card batch file</li> <li>- Card boot</li> </ul> | <ul style="list-style-type: none"> <li>- RAM disk</li> <li>- Built-in Ethernet</li> <li>- TCP/IP, UDP/IP socket communications</li> <li>- FTP client &amp; server</li> <li>- Network filter</li> <li>- Function removal</li> <li>- User LED</li> <li>- Advanced sampling trace</li> <li>- User authentication</li> <li>- User operation permissions</li> <li>- CPU operation permissions</li> <li>- Modbus TCP slave (server)</li> </ul> |  |
| Input relay                                    | X   | 4,096 points  |  |  |
| Output relay                                   | Y   | 8,192 points  |  |  |
| Internal relay                                 | I   | 16,384 points   |  |  |
| Shared relay                                   | E   | 2,048 points  |  |  |
| Extended shared relay                          |   | 2,048 points  |  |  |
| Link relay                                     | L   | 8,192 points  |  |  |
| Special relay                                  | M   | 9,984 points  |  |  |
| Timer  | T   | 100μs timer *1  | 2,048 points   |  |
|  |   | 1ms, 10ms, 100ms timer  |  |  |
| Continuous                                     |   | 3,072 points  |  |  |
| Counter  | C   |   |  |  |
| Data register                                  | D   | 16,384 points   |  |  |
| File register                                  | latched B   | 32,768 points   |  |  |
| Link register                                  | W   | 8,192 points  |  |  |
| Special register                               | Z   | 1,024 points  |  |  |
| Index register                                 | V   | 256 points  |  |  |
| Shared register                                | R   | 1,024 points  |  |  |
| Extended shared register                       |   | 3,072 points  |  |  |
| Cache register                                 | F   | 131,072 points  | 524,288 points   |  |
| Label  | -   | 1,024   |  |  |
| Interrupt handler routine                      | -   | 4   |  |  |
| Constant                                       | Decimal   | -   | for 16-bit instruction: -32,768 to 32,767 for 32-bit instruction: -2,147,483,648 to 2,147,483,647  | Same as specifications on left, plus for 64-bit instruction: -9,223,372,036,854,775,808 to 9,223,372,036,854,775,807 |
|  | Hexadecimal   | -   | for 16-bit instruction: \$0 to \$FFFF for 32-bit instruction: \$0 to \$FFFFFFFF  | Same as specifications on left, plus for 64-bit instruction: \$0 to \$FFFFFFFFFFFFFFFF                               |
|  | String  | -   | 16-bit instruction e.g. "AB" 32-bit instruction e.g. "ABCD"  | Same as specifications on left, plus Constant definition (max. 255 char.)  |
|  | Binary  | -   | -  | Constant definition (256 contiguous bytes max.)  |
|  | IEEE single precision floating-point  | -   | 32-bit instruction e.g. 1.23, -3.21 approx. -3.4x10 <sup>38</sup> to 3.4x10 <sup>38</sup>  | Same as specifications on left, plus Constant definition   |
|  | IEEE double precision floating-point  | -   | -  | 64-bit instruction e.g. 1.23, -3.21 approx. -1.79x10 <sup>308</sup> to +1.79x10 <sup>308</sup> Constant definition   |
| Constant index                                 | -   | 0 to 2,047  |  |  |

\*1: Up to 16 points configurable.

### Common Specifications

| Item                     | Specifications                  |   |
|--------------------------|---------------------------------|---|
| Environment              | Operating ambient temperature*1 | 0 to 55°C   |
|                          | Operating ambient humidity      | 10 to 90%RH (no condensation allowed)   |
|                          | Ambient storage temperature     | -20 to 75°C   |
|                          | Ambient storage humidity        | 10 to 90%RH (no condensation allowed)   |
|                          | Operating atmosphere            | No corrosive gas, no excessive amount of dust   |
|                          | Grounding                       | AC Power supply module : Protective earth (Comply with the regulation of each country.)<br>DC Power supply module : Functional earth  |
|                          | Noise immunity                  | Noise voltage 1,500Vp-p, measured by noise simulator with noise width of 1μs, rise time of 1ns and repeating frequency of 25 to 60Hz  |
|                          | Vibration strength              | Conforms to JIS C60068-2-6, frequency 10 to 57Hz, amplitude 0.075mm<br>Frequency 57 to 150Hz, acceleration 9.8m/s <sup>2</sup><br>Swept 10 times in each X, Y and Z direction |
|                          | Mechanical shock resistance     | Conforms to JIS C60068-2-27, 147m/s <sup>2</sup> , 3 times in each of three directions (98m/s <sup>2</sup> when mounted on DIN rail)  |
|                          | Structure/<br>Appearance        | Structure   |
| Altitude of installation |                                 | Max. of 2000 m above sea level  |
| Cooling method           |                                 | Natural cooling   |
| Mounting method          |                                 | Direct (with 4 or 5 screws (M4, 12mm)), DIN rail (except for F3BU16-0N)   |
| Paint color              |                                 | Light cobalt blue: Munsell 6.2 PB4.6/8.8 or equivalent, lamp black: Munsell 0.8 Y2.5/0.4 or equivalent  |
| Weight                   |                                 | Approx. 2.4kg when 13-slot base module is fully occupied with contact modules   |

\*1: Some FA-M3 modules may have a narrower surrounding temperature range than 0-55°C. A system incorporating such modules must be used within the narrower surrounding temperature range for such modules.

### Power Supply Specifications

| Item                                   | Specifications  |           |           |  |           |           |
|--|---|-----------|-----------|--|-----------|-----------|
|  | F3PU10-0S   | F3PU20-0S | F3PU30-0S | F3PU16-0S  | F3PU26-0S | F3PU36-0S |
| Supply voltage range                   | 100to240V AC, single phase 50/60 Hz   |           |           | 24V DC   |           |           |
| Range of supply voltage change         | 85to264V AC 50/60Hz±3Hz   |           |           | 15.6to31.2V DC   |           |           |
| Power consumption                      | 35VA  | 85VA      | 100VA     | 15.4W  | 33.1W     | 46.2W     |
| Insulation resistance                  | 5MΩ min. when tested between a group of external AC terminals and the FG terminal using a 500VDC insulation resistance tester                               |           |           | 5MΩ min. when tested across a group of external DC terminals and the FG terminal using a 500VDC insulation resistance tester |           |           |
| Withstanding voltage                   | 1500V AC for one minute between a group of external AC terminals and the FG terminal  |           |           | 1500V AC for one minute between a group of external DC terminals and the FG terminal   |           |           |
| FAIL-signal contact output             | Located on the front terminal block of power supply module; contact ratings: 24V DC, 0.3 A (Equipped with both normally-open and normally-closed terminals) |           |           |  |           |           |
| Leakage current                        | 3.5mA max.  |           |           |  |           |           |
| Allowable momentary power failure time | 20ms  |           |           |  |           |           |

### Software

| Category           | Name  | Type Name | Specifications  |
|--------------------|---|-----------|---|
| Development tool   | FA-M3 Programming Tool WideField3 *1                        | SF630-MCW | Windows 7/ 8/ 8.1/ 10 (x86/x64) compatible, multi-lingual version, LiveLogicAnalyzer function*4, CD-ROM                         |
| Simulation         | FA-M3 Simulation Software Virtual-M3                        | SF681-MDW | Windows 7/ 8/ 8.1/ 10 (x86/x64) compatible, multi-lingual version, Web download   |
| Package            | WideField3 Simulation Package                               | SF631-MCW | Packaged product composed of FA-M3 Programming Tool WideField3 (SF630-MCW) and FA-M3 Simulation Software Virtual-M3 (SF681-MDW) |
| Configuration tool | ToolBox for Temperature Control and Monitoring Modules *2   | SF661-MCW | Windows 7/ 8/ 8.1/ 10 (x86/x64) compatible, multi-lingual version, CD-ROM (for F3CU04 and F3CX04)                               |
|                    | ToolBox for Positioning Modules *3 (for F3NC3□)             | SF662-MCW | Windows 7/ 8/ 8.1/ 10 (x86/x64) compatible, multi-lingual version, CD-ROM (for F3NC3□)  |
|                    | ToolBox for Positioning Modules (for F3YP2□)                | SF663-MCW | Windows 7/ 8/ 8.1/ 10 (x86/x64) compatible, multi-lingual version, CD-ROM (for F3YP2□)  |
|                    | FA-M3 Configurations Tool for EtherNet/IP Interface Modules | SF673-MDW | Windows7/10 compatible, multi-lingual version, Web download (Free of charge)  |

\*1: R2.01 and later versions are multi-lingual versions.

\*2: R6.01 and later versions are multi-lingual versions.

\*3: R4.01 and later versions are multi-lingual versions.

\*4: For F3SP71-4S/F3SP76-7S Only

### Hardware List

| Category     | Name   | Type name     | Specifications  |
|--------------|--|---------------|---|
| Base         | Base module *1   | F3BU04-0N     | For power supply (F3PU10/F3PU16) + 4 slots (CPU+I/O)  |
|              |  | F3BU05-0D     | For power supply (F3PU20/F3PU30/F3PU26/F3PU36) + 5 slots (CPU+I/O)  |
|              |  | F3BU06-0N     | For power supply (F3PU10/F3PU16) + 6 slots (CPU+I/O)  |
|              |  | F3BU09-0N     | For power supply (F3PU20/F3PU30/F3PU26/F3PU36) + 9 slots (CPU+I/O)  |
|              |  | F3BU13-0N     | For power supply (F3PU20/F3PU30/F3PU26/F3PU36) + 13 slots (CPU+I/O)   |
|              |  | F3BU16-0N *4  | For power supply (F3PU20/F3PU30/F3PU26/F3PU36) + 16 slots (CPU+I/O)   |
| Power supply | Power supply module  | F3PU10-0S     | 100 to 240V AC, 5V DC/2.0A rated output (for 4 and 6 slots, M4 screws)  |
|              |  | F3PU20-0S     | 100 to 240V AC, 5V DC/4.3A rated output (for 5, 9,13 and 16 slots, M4 screws)   |
|              |  | F3PU30-0S     | 100 to 240V AC, 5V DC/6.0A rated output (for 5, 9,13 and 16 slots, M4 screws)   |
|              |  | F3PU16-0S     | 24V DC, 5V DC/2.0A rated output (for 4 and 6 slots, M4 screws)  |
|              |  | F3PU26-0S     | 24V DC, 5V DC/4.3A rated output (for 5, 9, 13 and 16 slots, M4 screws)  |
|              |  | F3PU36-0S     | 24V DC, 5V DC/6.0A rated output (for 5, 9, 13 and 16 slots, M4 screws)  |
| CPU          | Sequence CPU module  | F3SP22-0S     | Ladder 10K steps, basic instruction 0.045μs or longer, with memory  |
|              |  | F3SP71-4S *8  | Ladder 60K steps, basic instruction 0.00375μs or longer, with network and Modbus/TCP slave (server) functions (USB2.0, Ethernet)  |
|              |  | F3SP76-7S *8  | Ladder 260K steps, basic instruction 0.00375μs or longer, with network and Modbus/TCP slave (server) functions (USB2.0, Ethernet) |
| Memory       | ROM pack   | RK33-0N       | Ladder 56K steps (for F3SP22)   |
|              |  | RK73-0N       | Ladder 120K steps (for F3SP22)  |
| Digital I/O  | Input module   | F3XA08-1N     | 100-120V AC, 8 points Terminal block  |
|              |  | F3XA08-2N     | 200-240V AC, 8 points Terminal block  |
|              |  | F3XA16-1N     | 100-120V AC, 16 points Terminal block   |
|              |  | F3XH04-3N     | High-speed input with pulse catch function, 24V DC, 4 points Terminal block   |
|              |  | F3XC08-0N     | No-voltage contact input, 8 points Terminal block   |
|              |  | F3XC08-0C     | No-voltage contact input, 8 points, separate commons Terminal block   |
|              |  | F3XD08-6F     | DC input, 12-24V DC, 8 points Terminal block  |
|              |  | F3XD16-3F     | DC input, 24V DC, 16 points Terminal block  |
|              |  | F3XD16-4F     | DC input, 12V DC, 16 points Terminal block  |
|              |  | F3XD16-3H     | DC input, positive common, 24V DC, 16 points (high-speed input) Terminal block  |
|              | Pulse input module   | F3XD32-3F     | DC input, 24V DC, 32 points Connector *2  |
|              |  | F3XD32-4F     | DC input, 12V DC, 32 points Connector *2  |
|              |  | F3XD32-5F     | TTL input, 5V DC, 32 points Connector *2  |
|              |  | F3XD64-3F     | DC input, 24V DC, 64 points Connector *2  |
|              |  | F3XD64-4F     | DC input, 12V DC, 64 points Connector *2  |
|              |  | F3XD64-6M     | DC input, 12 to 24V DC, 64 points (8x8) Connector *2  |
|              |  | F3XS04-3N     | Ring-up counter, 0 to 20kHz, 24V DC input, 16-bit channel x 4 Terminal block  |
|              |  | F3XS04-4N     | Ring-up counter, 0 to 20kHz, 12V DC input, 16-bit channel x 4 Terminal block  |
|              |  | F3YA08-2N     | Triac output (100 to 240V AC), 1 A, 8 points Terminal block   |
|              |  | Output module | F3YC08-0C *7  |
| F3YC08-0N *7 | Relay output (5 to 24V DC, 100 to 240V AC), 2A, 8 points Terminal block  |               |   |
| F3YC16-0N *7 | Relay output (5 to 24V DC, 100 to 240V AC), 2A, 16 points Terminal block |               |   |
| F3YD04-7N    | TR output, 24V DC, 2A, isolated commons, 4 points Terminal block         |               |   |
| F3YD08-6A    | TR sink output, 12 to 24V DC, 1A, 8 points Terminal block                |               |   |
| F3YD08-6B    | TR source output, 12 to 24V DC, 1A, 8 points Terminal block              |               |   |
| F3YD08-7A    | TR sink output, 12 to 24V DC, 2A, 8 points Terminal block                |               |   |



| Category                      | Name   | Type name   | Specifications   |  |
|-------------------------------|--|---|--|--|
| Digital I/O                   | Output module  | F3YD14-5A   | TR sink output, 12 to 24V DC, 0.5A, 14 points  | Terminal block   |
|                               |  | F3YD14-5B   | TR source output, 12 to 24V DC, 0.5A, 14 points  | Terminal block   |
|                               |  | F3YD32-1H   | High speed TR sink output, 12 to 24V DC, 0.1A, 32 points, with output short-circuit protection                         | Connector *2   |
|                               |  | F3YD32-1P   | TR sink output, 12 to 24V DC, 0.1A, 32 points, with output short-circuit protection                                    | Connector *2   |
|                               |  | F3YD32-1R   | TR source output, 12 to 24V DC, 0.1A, 32 points, with output short-circuit protection                                  | Connector *2   |
|                               |  | F3YD32-1T   | TTL output, 5V DC, 16mA, 32 points   | Connector *2   |
|                               |  | F3YD64-1M   | TR output, matrix scan, 12 to 24V DC, 64 points (8x8)  | Connector *2   |
|                               |  | F3YD64-1P   | TR sink output, 12 to 24V DC, 0.1A, 64 points, with output short-circuit protection                                    | Connector *2   |
|                               |  | F3YD64-1R   | TR source output, 12 to 24V DC, 0.1A, 64 points, with output short-circuit protection                                  | Connector *2   |
|                               |  | I/O module  | F3WD64-3P  | DC Input, TR sink output, 0.1A, 24V DC, 32 points each, with output short-circuit protection |
| F3WD64-4P                     | DC Input, TR sink output, 0.1A, 12V DC, 32 points each, with output short-circuit protection |   | Connector *2   |  |
| Analog I/O                    | Analog input module  | F3AD04-5V   | 0 to 5V DC,1 to 5V DC,-10 to 10V DC,0 to 10V DC, 4 points,12bitA/D Sampling period 1ms                                 | Terminal block   |
|                               |  | F3AD04-5R   | 0 to 5V DC,1 to 5V DC,-10 to 10V DC,0 to 10V DC,Input 4 points,16bitA/D, Sampling period 50µs                          | Terminal block   |
|                               |  | F3AD08-5V   | 0 to 5V DC,1 to 5V DC,-10 to 10V DC,0 to 10V DC, 8 points,12bitA/D, Sampling period 1ms                                | Terminal block   |
|                               |  | F3AD08-4W   | 0 to 20mA,4 to 20mA, 8 points,12bitA/D, Sampling period 1ms  | Terminal block   |
|                               |  | F3AD08-4R   | 0 to 20mA,4 to 20mA input, 8 points, 16-bit high-res. ADC, sampling at 50µs/point                                      | Terminal block   |
|                               |  | F3AD08-5R   | 0 to 5V,0 to 10V,1 to 5V,-10 to 10V DC input, 8 points, 16-bit high res. ADC, sampling at 50µs/point                   | Terminal block   |
|                               | Analog output module   | F3AD08-6R   | 0 to 5V,1 to 5V,-10 to 10V DC,0 to 20mA,4 to 20mA input, 8 points, 16-bit high res. ADC, sampling at 50µs/point        | Terminal block   |
|                               |  | F3DA04-6R   | -10 to 10V, 0 to 10V, 0 to 5V, 1 to 5V, 4 to 20mA, 0 to 20mA and -20 to 20mA DC output, 4 points, 16-bit high-res. DAC | Terminal block   |
|                               |  | F3DA08-5R   | -10 to 10V, 0 to 10V, 0 to 5V, 1 to 5V DC output, 8 points, 16-bit high-res. DAC                                       | Terminal block   |
|                               |  | Temperature control and PID module  | F3CU04-0S  | 4 universal inputs (TC, RTD or voltage), 100ms for 2 channels or 200ms for 4 channels        |
| F3CU04-1S                     | 4 to 20mA continuous output in addition to the functions of F3CU04-0N                        |   | Terminal block   |  |
| Temperature monitoring module | F3CX04-0N  | 4 universal inputs (TC, RTD or voltage)   | Terminal block   |  |
| Data acquisition              | High-speed data acquisition module   | F3HA06-1R   | -10 to 10V, 0 to 10V, 1 to 5V, -5V to 5V, -2.5 to 2.5V, input 6 points, 5µs, data buffer 2M words                      | Terminal block   |
|                               |  | F3HA12-1R   | -10 to 10V, 0 to 10V, 1 to 5V, -5V to 5V, -2.5 to 2.5V, input 12 points, 5µs, data buffer 2M words                     | Terminal block   |
| Communications                | Ethernet interface module  | F3LE01-1T   | 10Mbps, 10BASE-T, with higher-level link and event transmission functions  | Connector  |
|                               |  | F3LE11-1T   | 10/100Mbps, 10BASE-T/100BASE-TX, with E-mail function  | Connector  |
|                               |  | F3LE12-1T   | 10/100Mbps, 10BASE-T/100BASE-TX, with higher-level link, (UDP/IP)messaging function                                    | Connector  |
|                               | NX Interface module  | F3NX01-2N   | 10/100Mbps, 10BASE-T/100BASE-TX, with Autonomous Distribution*3 protocol   | Connector  |
|                               | EtherNet/IP Interface Module   | F3LN01-0N   | 10/100Mbps,10BASE-T/100BASE-TX,EtherNet/IP scanner/adapter   | Connector  |
|                               | FL-net interface module  | F3LX02-2N *5  | 10/100Mbps, 10BASE-T/100BASE-TX, FL-net (OPCN-2) protocol Ver. 2.00  | Connector  |
|                               | DeviceNet interface module   | F3LD01-0N   | 500kbps max., DeviceNet port x 1, with master/scanner function   | Connector  |
|                               | CAN2.0B Interface Module   | F3LD21-0N   | CAN2.0B Protocol, 1Mbps max, 1 channel   | Connector  |
|                               | Modbus Interface Module  | F3LC31-2F   | Modbus RTU/ASCII, 115.2kbps max, 1 port  | Terminal block   |
|                               | GP-IB communications module  | F3GB01-0N   | GP-IB port x 1   | Connector  |
|                               | Personal computer link module  | F3LC11-1F   | 115.2kbps max., RS-232-C port x 1, with modem interface function   | Connector  |
|                               |  | F3LC11-2F   | 115.2kbps max., RS-422/RS-485 port x 1   | Terminal block   |
|                               |  | F3LC12-1F   | 115.2kbps max., RS-232-C port x 2, with modem interface function   | Connector  |
|                               | Ladder communications module   | F3RZ81-0F   | 115.2kbps max., RS-232C port x 1   | Connector  |
|                               |  | F3RZ82-0F   | 115.2kbps max., RS-232C port x 2   | Connector  |
| F3RZ91-0F                     |  | 115.2kbps max., RS-422/RS-485 port x 1  | Terminal block   |  |
| UT link module                | F3LC51-2N  | RS-422 / RS-485 port x 1, allows easy connection of digital indicating controller | Terminal block   |  |
| FA link H2 module             | F3LP32-0N*10   | 32 stations max., total transmission distance 1km, 1.25Mbps max.                  | Terminal block   |  |

| Category   | Name   | Type name  | Specifications  |                |
|--|--|--|---|----------------|
| Remote I/O   | YHLS master module                                   | F3LH01-1N  | 12Mbps max., YHLS port x 1  | Terminal block |
|  |  | F3LH02-1N  | 10/100Mbps,10BASE-T/100BASE-TX,EtherNet/IP scanner/adapter  | Connector      |
|  | Fiber-optic FA-bus module                            | F3LR01-0N  | 7 stations max., total transmission distance 200m, 10Mbps max.  | Connector      |
|  | Fiber-optic FA-bus Type 2 module                     | F3LR02-0N  | 32 stations max., total transmission distance 1.4km, max. distance betw. stations 500m*9, 10Mbps max.   | Connector      |
|  | FA-bus Type 2 module                                 | F3LR02-1W  | 7 stations max., max. transmission distance: 70m for daisy-chain configuration and 80m for loop configuration, max. distance between stations 10m, 10Mbps max., wired | Terminal block |
| Counter/positioning                                  | High-speed counter module                            | F3XP01-0H  | Up/down counter, phase difference, pulse + direction, addition/subtraction, 400kpps (for x4), 32-bit channel x 1  | Connector *2   |
|  |  | F3XP02-0H  | Up/down counter, phase difference, pulse + direction, addition/subtraction, 400kpps (for x4), 32-bit channel x 2  | Connector *2   |
|  | Positioning module (with multi-channel pulse output) | F3YP22-0P  | 2-axis control, 7,996kpps max. for servo/DD/Linear motor control, 1,999kpps. for stepping motor control   | Connector      |
|  |  | F3YP24-0P  | 4-axis control, 7,996kpps max. for servo/DD/Linear motor control, 1,999kpps. for stepping motor control   | Connector      |
|  |  | F3YP28-0P  | 8-axis control, 7,996kpps max. for servo/DD/Linear motor control, 1,999kpps. for stepping motor control   | Connector      |
|  | Positioning module (with pulse output)               | F3NC32-0N  | 2-axis control, 5Mpps max. pulse output, PTP and linear/circular interpolation, direct/pattern operation, counter for ABS encoder input (2ch)                         | Connector *2   |
|  |  | F3NC34-0N  | 4-axis control, 5Mpps max. pulse output, PTP and linear/circular/helical interpolation, direct/pattern operation, counter for ABS encoder input (4ch)                 | Connector *2   |
|  | Positioning module (with analog voltage output)      | F3NC51-0N  | 1-axis control with speed reference voltage output type   | Connector *2   |
|  |  | F3NC52-0N  | 2-axis control with speed reference voltage output type   | Connector *2   |
| Positioning module (with MECHATROLINK-II interface)  | F3NC96-0N  | 15-axis control with MECHATROLINK-II *6 interface  | Connector   |                |
| Positioning module (with MECHATROLINK-III interface) | F3NC97-0N  | 15-axis control with MECHATROLINK-III *6 interface | Connector   |                |

\*1: The rail mount kit must be purchased separately.  
 \*2: Connector for external connection and connector cover must be purchased separately.  
 \*3: Autonomous Distribution® is a registered trademark of Hitachi, Ltd.  
 \*4: This unit cannot be used with the rail mount kit.  
 \*5: F3LX02-1N is not compatible with F3LX01-0N. Contact Yokogawa sales office for F3LX01-0N.  
 \*6: MECHATROLINK is a trademark of the MECHATROLINK Members Association.  
 \*7: Relays of relay output modules are not of hermetically sealed type so their service life may be affected by dust or corrosive gases. When switched on/off in an atmosphere containing silicone gases from silicone-based materials, these relays may suffer from poor electrical contact due to SiO2 (silicon dioxide) deposits, especially under load conditions below 24V DC and 500mA for which transistor output or other modules employing semiconductor elements are recommended.  
 \*8: Unlike the older F3SP7□-□N models, F3SP7□-□S models have no special restriction on the number of CPU modules for specific CPU module combinations in a multi-CPU configuration and are compatible with the FA Link H module (F3LP02-0N).  
 \*9: It is necessary to confirm with Sumitomo Electric Industries, Ltd. about the production of cables that are compliant with the module specifications. The maximum distance between stations 500m is the specification when using KM67 (discontinued product).  
 \*10: Only F3LP32-0N modules can be connected with each other. F3LP32-0N modules cannot be connected to F3LP01-0N or F3LP02-0N modules.  
 (Note) For coating treatment, contact Yokogawa's sales office.

### Peripheral Devices

| Category                          | Name  | Type name  | Specifications  |
|-----------------------------------|---|--|---|
| Peripheral Devices                | CPU port / D-sub 9-pin conversion cable             | KM10-0C  | D-sub 9-pin, female, cable length approx. 0.5m (for F3SP22-0S)  |
|                                   | Cable for programming tool *1                       | KM11-2T  | DOS/V compatible, cable length approx. 3m   |
|                                   |   | KM13-1S  | USB 1.1 compliant USB-serial converter, cable length approx. 3m   |
|                                   | Monitor cables                                      | KM21-2A *2   | CPU port / D-sub 25-pin, male, cable length 3 m (for F3SP22-0S)   |
|                                   |   | KM21-2B *2   | CPU port / D-sub 9-pin, female, cable length 3 m (for F3SP22-0S)  |
|                                   | Cable for fiber-optic FA-bus (for use inside panel) | KM60-S06   | For use inside panel, cable length approx. 0.6m   |
|                                   |   | KM60-001   | For use inside panel, cable length approx. 1m   |
|                                   |   | KM60-003   | For use inside panel, cable length approx. 3m   |
|                                   | Cable for fiber-optic FA-bus (for indoor use)       | KM61-□□□   | For indoor use  |
|                                   |   | KM65-□□□   | For indoor use  |
|                                   | Cable for fiber-optic FA-bus (for outdoor use)      | KM62-□□□   | For outdoor use   |
|                                   |   | KM69-□□□   | Flame-retardant cable(equivalent of VW-1), For outdoor use  |
|                                   | YHLS slave units (TAH series)                       | TAHWD32-3PAM   | 16 DC inputs (positive common), 24V DC, MIL, 16 TR outputs (sink-type, with short-circuit protection), 24V DC 0.1A, MIL   |
|                                   |   | TAHWD32-3NBM   | 16 DC inputs (negative common), 24V DC, MIL, 16 TR outputs (source-type, with short-circuit protection), 24V DC 0.1A, MIL |
|                                   |   | TAHXD16-3PEM   | 16 DC inputs (positive common), 24V DC, MIL   |
|                                   |   | TAHXD16-3NEM   | 16 DC inputs (negative common), 24V DC, MIL   |
|                                   |   | TAHYD16-3EAM   | 16 TR outputs (sink-type, with short-circuit protection), 24V DC 0.1A, MIL  |
|                                   |   | TAHYD16-3EBM   | 16 TR outputs (source-type, with short-circuit protection), 24V DC 0.1A, MIL  |
|                                   | YHLS communication cables                           | KM80-□□□   | Flame-retardant cable(equivalent of VW-1), YHLS fixed cable   |
|                                   |   | KM81-□□□   | Flame-retardant cable(equivalent of VW-1), YHLS flexible cable  |
|                                   | Terminal block unit                                 | TA40-0N  | Converts 40 point I/O connector to European type terminal block.  |
|                                   | Conector terminal block                             | TA50-0N  | Connector terminal block (40 points), M3.5 screw  |
|                                   |   | TA50-2N  | Connector terminal block (40 points), M3 screw  |
| Cable for conector terminal block | KM55-□□□  | Cable between module and terminal block, length from 0.5m (-005) to 3m (-030) in 0.5m increments |   |
| Blank module                      | F3BL00-0N   | For empty I/O slots  |   |
| Input simulator switch            | S9307UF   | Simulator switch for input terminals (for F3XD32-□F, F3XD64-□F, F3WD64-□□)                       |   |

\*1: These cables for programming tools cannot be used with F3SP71 and F3SP76 CPU modules.

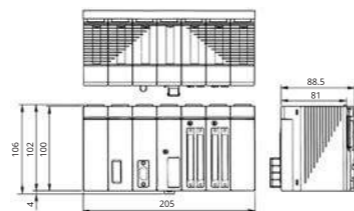
\*2: The cable is to be connected to the programming tool port located on the front panel of F3SP22 for higher-level linkservice (personal computer link functions). It is not to be used for online connection to FA-M3 programming tool WideField3.

### External Dimensions

Unit: mm

| Base module | Number of slots | Number of I/O slots* | Total width |
|-------------|-----------------|----------------------|-------------|
| F3BU04      | 4               | 3                    | 147         |
| F3BU05      | 5               | 4                    | 205         |
| F3BU06      | 6               | 5                    | 205         |
| F3BU09      | 9               | 8                    | 322         |
| F3BU13      | 13              | 12                   | 439         |
| F3BU16      | 16              | 15                   | 527         |

\* The number of available I/O slots is indicated assuming that one CPU module is installed.



### Manuals

| Name   | Document No.    |
|--|-----------------|
| Hardware Manual  | IM 34M06C11-01E |
| USB-Serial Converter   | IM 34M06C91-01E |
| High-speed Data Acquisition Module (F3HA06-1R, F3HA12-1R)  | IM 34M06G02-02E |
| Analog Input Modules   | IM 34M06H11-02E |
| Analog Output Modules (F3DA04-6R, F3DA08-5R)   | IM 34M06H11-03E |
| Ladder Communication Modules (for F3RZ81-0F, F3RZ82-0F, F3RZ91-0F)   | IM 34M06H22-02E |
| Ethernet Interface Module(F3LE01-1T)   | IM 34M06H24-06E |
| Ethernet Interface Module(F3LE11-1T)   | IM 34M06H24-07E |
| Ethernet Interface Module(F3LE12-1T)   | IM 34M06H24-08E |
| UT Link Module   | IM 34M06H25-01E |
| DeviceNet Interface Module   | IM 34M06H28-01E |
| NX Interface Module (F3NX01-2N)  | IM 34M06H29-02E |
| FL-net (OPCN-2) Interface Module   | IM 34M06H32-03E |
| EtherNet/IP Interface Module   | IM 34M06H36-01E |
| CAN2.0B Interface Module   | IM 34M06H37-01E |
| Personal Computer Link Modules   | IM 34M06H41-02E |
| Modbus Interface Module  | IM 34M06H42-01E |
| FA-Link H2 Module and Fiber-optic FA-Link H Module   | IM 34M06H43-02E |
| Fiber-optic FA-bus Module and Fiber-optic FA-bus Type 2 Module   | IM 34M06H45-01E |
| YHLS Slave Units (TAH Series)  | IM 34M06H46-03E |
| YHLS Master Module (F3LH01-1N, F3LH02-1N)  | IM 34M06H46-04E |
| High-speed Counter Modules   | IM 34M06H53-01E |
| Pulse Input Module   | IM 34M06H54-01E |
| Positioning Modules (with Multi-channel Pulse Output) (F3YP22-0P, F3YP24-0P,F3YP28-0P)                         | IM 34M06H55-04E |
| Positioning Modules (with Pulse Output)  | IM 34M06H56-02E |
| Positioning Modules (with Analog Voltage Output)   | IM 34M06H58-01E |
| Positioning Modules (with MECHATROLINK-II Interface)   | IM 34M06H60-02E |
| Positioning Modules (with MECHATROLINK-III Interface)  | IM 34M06H60-03E |
| Temperature Control and PID Module (F3CU04-0S, F3CU04-1S)  | IM 34M06H62-02E |
| Temperature Monitoring Module  | IM 34M06H63-01E |
| Sequence CPU - Instructions  | IM 34M06P12-03E |
| Sequence CPU - Functions (for F3SP22-0S, F3SP28-3N/3S, F3SP38-6N/6S, F3SP53-4H/4S, F3SP58-6H/6S and F3SP59-7S) | IM 34M06P13-01E |
| Sequence CPU - Functions (for F3SP71-4N/4S, F3SP76-7N/7S)  | IM 34M06P15-01E |
| Sequence CPU - Network Functions (for F3SP71-4N/4S, F3SP76-7N/7S)  | IM 34M06P15-02E |
| Sequence CPU - Modbus /TCP Slave Functions   | IM 34M06P15-03E |
| Personal Computer Link Commands  | IM 34M06P41-01E |
| FA-M3 Programming Tool WideField3 (Introduction and troubleshooting) *1  | IM 34M06Q16-01E |
| FA-M3 Programming Tool WideField3 (Offline) *1   | IM 34M06Q16-02E |
| FA-M3 Programming Tool WideField3 (Online) *1  | IM 34M06Q16-03E |
| FA-M3 Programming Tool WideField3 (Script) *1  | IM 34M06Q16-04E |
| FA-M3V Environment Tool Trace Function*1   | IM 34M06Q50-21E |
| FA-M3 Simulation Software Virtual-M3   | IM 34M06Q50-22E |
| FA-M3 ToolBox Manual *1  | IM 34M06Q30-01E |
| FA-M3 ToolBox for Positioning Modules*(for F3NC32-0N, F3NC34-0N)   | IM 34M06Q31-01E |
| FA-M3 ToolBox for Positioning Modules*(for F3YP22-0P, F3YP24-0P, F3YP28-0P)                                    | IM 34M06Q31-03E |
| FA-M3 ToolBox for Temperature Control and Monitoring Modules *1  | IM 34M06Q31-02E |

\*1: Supplied with the software package as PDF file. Paper documentation can be ordered separately if necessary.



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- For proper and safe use of this product, read the instruction manual thoroughly.
- If faults of this product are expected to result in accidents or losses, install additional external protection and/or safety circuits.
- If the product is to be used in applications which may directly affect or threaten human lives and safety, such as railway facilities, aviation and space navigation, medical equipment or transport equipment, please contact Yokogawa's sales office.



Synaptic Business Automation underlies a process of co-innovation and collaboration with customers that leverages Yokogawa's domain knowledge and digital automation technologies to create sustainable value.

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[Ed : 08/b] Printed in Japan, 907 (VC)